

Minimal Obstructions for Partial Representations of Interval Graphs*

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Abstract. *Interval graphs* are intersection graphs of closed intervals. A generalization of recognition called *partial representation extension* was introduced recently. The input gives an interval graph with a *partial representation* specifying some pre-drawn intervals. We ask whether the remaining intervals can be added to create an *extending representation*. Two linear-time algorithms are known for solving this problem.

In this paper, we characterize the *minimal obstructions* which make partial representations non-extendible. This generalizes Lekkerkerker and Boland's characterization of the minimal forbidden induced subgraphs of interval graphs. Each minimal obstruction consists of a forbidden induced subgraph together with at most four pre-drawn intervals. A Helly-type result follows: A partial representation is extendible if and only if every quadruple of pre-drawn intervals is extendible by itself. Our characterization leads to a linear-time certifying algorithm for partial representation extension.

*This is the revised version from 29th December 2015. The conference version of this paper appeared in ISAAC 2014 [24]. For an interactive structural diagram of this paper, see <http://pavel.klavik.cz/orgpad/minobstr.html> (supported for Firefox and Google Chrome).

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1 Introduction

The main motivation for graph drawing and geometric representations is finding ways to visualize some given data efficiently. The most famous representations are plane drawings, in which we draw a graph in the plane and we want to avoid (or minimize) crossings of edges. However, for certain types of graphs, *intersection representations* are more suitable. They represent each vertex by a geometrical object and encode the edges by intersections.

1.1 Interval Graphs

The most studied class of intersection graphs are *interval graphs* (INT), defined by Hájos [13] in 1957. An *interval representation* \mathcal{R} is a collection of closed intervals $\{\langle x \rangle : x \in V(G)\}$ where $\langle x \rangle \cap \langle y \rangle \neq \emptyset$ if and only if $xy \in E(G)$. A graph is an interval graph if it has an interval representation; see Fig. 1a.

Interval graphs have many applications. Already in 1959, Benzer [3] used them in his experimental study of DNA. For some time, interval graphs played an important role for the DNA hybridization [16], in which short pieces of DNA are studied independently. Further applications include scheduling, psychology, archaeology, etc. [34,31,17].

Interval graphs also have nice theoretical properties. They are perfect and closely related to path-width decompositions. They can be recognized in linear time [5,9,28], and many hard combinatorial problems are polynomially solvable for interval graphs. Fulkerson and Gross [12] characterized them by consecutive orderings of maximal cliques (see Section 3 for details). This lead Booth and Lueker [5] to the construction of PQ-trees, which are an efficient data structure to deal with consecutive orderings, and have many other applications.

Chordal graphs (CHOR) are graphs with no induced cycle of length four or more, alternatively intersection graphs of subtrees of trees. Three vertices form an *asteroidal triple* if there exists a path between every pair of them avoiding the neighborhood of the third vertex. *Asteroidal triple-free graphs* (AT-FREE)

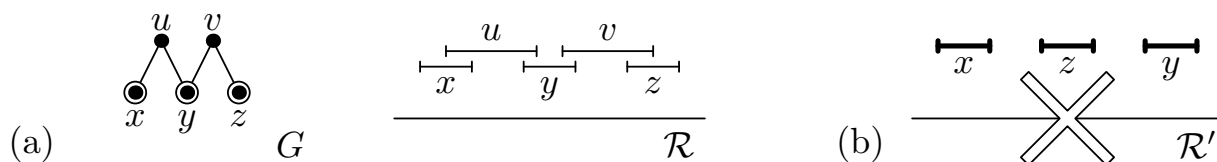


Fig. 1. (a) An interval graph G with one of its interval representations \mathcal{R} . (b) A partial representation \mathcal{R}' with pre-drawn intervals $\langle x \rangle'$, $\langle y \rangle'$ and $\langle z \rangle'$. It is non-extendible since $\langle u \rangle$ cannot be placed. In all figures, we depict pre-drawn intervals in bold.

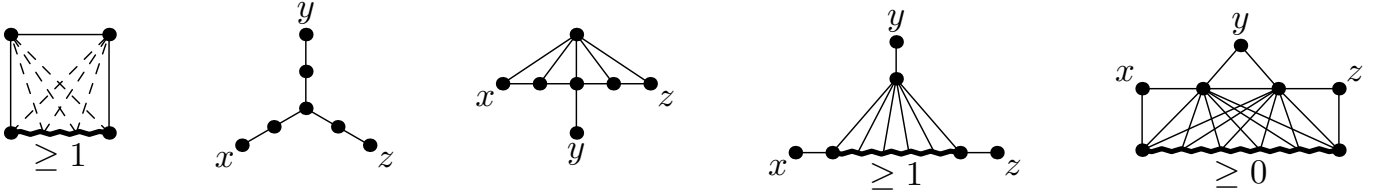


Fig. 2. Five types of LB obstructions which are the minimal forbidden induced subgraphs of INT. The bold curly lines correspond to induced paths with denoted minimal lengths. The leftmost obstructions are induced cycles of length four or more. The remaining four types of obstructions are minimal asteroidal triples (x, y, z) which are chordal graphs.

are graphs containing no asteroidal triples. Lekkerkerker and Boland [26] characterized interval graphs as $\text{INT} = \text{CHOR} \cap \text{AT-FREE}$. They described this characterization by the minimal forbidden induced subgraphs given in Fig. 2 which we call *Lekkerkerker-Boland obstructions* (LB).

1.2 Partial Representation Extension

The partial representation extension problem was introduced by Klavík et al. [22]. A *partial representation* \mathcal{R}' of G is an interval representation $\{\langle x \rangle' : x \in V(G')\}$ of an induced subgraph G' of G . The vertices of G' and the intervals of \mathcal{R}' are called *pre-drawn*. A representation \mathcal{R} of G *extends* \mathcal{R}' if and only if it assigns the same intervals to the vertices of G' , i.e., $\langle x \rangle = \langle x \rangle'$ for every $x \in V(G')$. For an example, see Fig. 1b.

Problem: Partial Representation Extension – REPEXT(INT)
Input: A graph G and a partial representation \mathcal{R}' of G' .
Output: Is there an interval representation of G extending \mathcal{R}' ?

The first polynomial-time algorithm, running in $\mathcal{O}(n^2)$ time, was given in [22]. Currently, there are two different linear-time algorithms [4,21] for this problem.

We note that the partial representation extension problems have been considered also for other classes of intersection graphs. A linear-time algorithm for proper interval graphs and an almost quadratic-time algorithm for unit interval graphs are given in [19], and improved to quadratic time in [33]. The partial representation extension problems are polynomial-time solvable for k -nested interval graphs (classes generalizing proper interval graphs), but NP-hard for k -length interval graphs (classes generalizing unit interval graphs), even for $k = 2$ [23]. Polynomial-time algorithms are further known for circle graphs [7], and permutation and function graphs [18]. The partial representation extension problems for chordal graphs [20] and contact representations of planar

graphs [6] are NP-hard. Notable graph classes for which the complexity of the partial representation extension problem is open are circular-arc graphs and trapezoid graphs.

Outside intersection graphs, the similar problem was considered even sooner for planar graphs. Partially embedded planar graphs can be extended in linear time [1]. Even though every planar graph has a straight-line embedding, extension of such embeddings is NP-hard [29]. Kuratowski's characterization of minimal forbidden minors was extended to partially embedded planar graphs by Jelínek et al. [15]. Our research has a similar spirit as this last result.

1.3 Our Results

In this paper, we generalize the characterization of Lekkerkerker and Boland [26] to describe minimal obstruction which make partial representations non-extendible. Each obstruction consists of a small graph and its non-extendible partial representation. Aside LB obstructions, we have two trivial obstructions, called SE, and ten infinite classes of minimal obstructions. The main class, called k -FAT obstructions, has three wrongly ordered disjoint pre-drawn intervals $\langle x_k \rangle'$, $\langle y_k \rangle'$, and $\langle z_k \rangle'$. The obstruction consists of a zig-zag structure with k levels where the last level cannot be placed. See Fig. 3a and b for 1-FAT and 2-FAT obstructions. There are eight other infinite classes derived from k -FAT obstructions by adding a few vertices and having different vertices pre-drawn. The last infinite class of (k, ℓ) -CE obstructions consists of a k -FAT obstruction glued with an ℓ -FAT obstruction and contains only two pre-drawn vertices; see Fig. 3c for a $(1, 1)$ -CE obstruction. We formally define these minimal obstructions in Section 2.

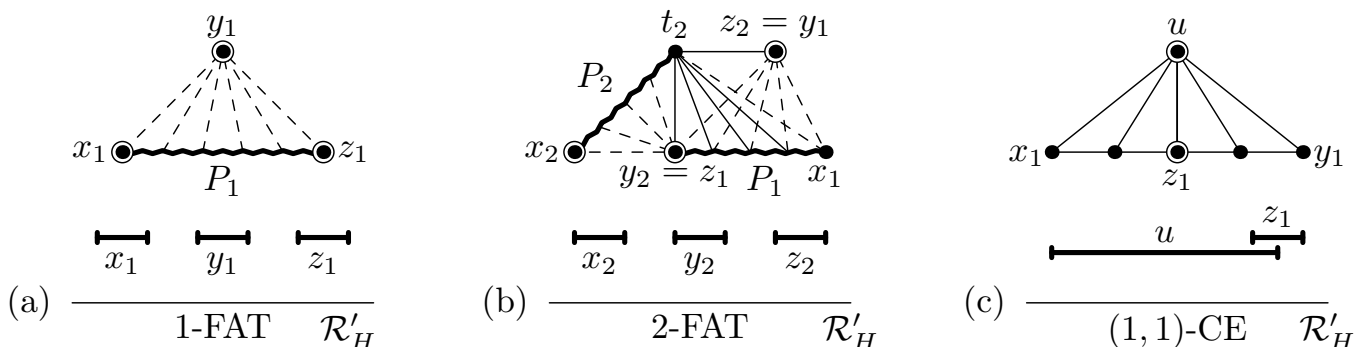


Fig. 3. Three examples of minimal obstructions, each consisting of a graph H and a non-extendible partial representation \mathcal{R}'_H . Curly lines denote induced paths and dashed edges are non-edges. The obstructions (a) and (b) are the first two k -FAT obstructions, and (c) is the simplest (k, ℓ) -CE obstruction.

Theorem 1.1. *A partial representation \mathcal{R}' of G is extendible if and only if G and \mathcal{R}' contain no LB, SE, k -FAT, k -BI, k -FS, k -EFS, k -FB, k -EFB, k -FDS, k -EFDS, k -FNS and (k, ℓ) -CE obstructions.*

Since every minimal obstruction contains at most four pre-drawn intervals, we get the following Helly-type result as a straightforward corollary:

Corollary 1.2. *A partial representation is extendible if and only if every quadruple of pre-drawn intervals is extendible by itself.*

All known algorithms for the partial representation extension problems [22,18,4,21,19,20] are able to certify solvable instances by outputting an extending representation. Using our minimal obstructions, we construct the first algorithm for partial representation extension certifying also non-extendible partial representations.³

Corollary 1.3. *Assume that the input gives the endpoints in a partial representation sorted from left to right. Then there exists an $\mathcal{O}(n + m)$ certifying algorithm for the partial representation extension problem, where n is the number of vertices and m is the number of edges of the input graph. If the answer is “yes”, it outputs an extending representation. If the answer is “no”, it detects one of the minimal obstructions.*

Outline. In Section 2, we define the minimal obstructions which make a partial representation non-extendible. In Section 3, we introduce the standard tools for working with interval graphs: the characterization of Fulkerson and Gross by linear orderings of maximal cliques, and the related data structure called an MPQ-trees which stores all feasible orderings.

In Section 4, we restate the characterization of [21]: a partial representation is extendible if and only if there exists a feasible ordering of the maximal cliques which extends a certain partial ordering \triangleleft . Therefore, to solve REPEXT(INT), we test whether the MPQ-tree can be reordered according \triangleleft .

Based on this, in Section 5, we build our strategy for showing that every non-extendible partial representation contains one of the defined minimal obstructions. If reordering of the MPQ-tree according to \triangleleft fails, then it fails in a

³Formally speaking, a polynomial-time algorithm certifies unsolvable instances by outputting “no” and by a proof of its correctness. Our algorithm outputs a simple proof that a given partial representation is non-extendible in terms of a minimal obstruction. This proof can be independently verified which is desirable.

leaf, in a P-node, or a Q-node. We deal with these three cases in Sections 6, 7, and 8, respectively, where the last one is most involved. In Section 9, we put these results together and establish Theorem 1.1 and Corollaries 1.2 and 1.3.

We conclude with a discussion of our results and several open problems.

1.4 Preliminaries

For a graph G , we denote by $V(G)$ its vertices and by $E(G)$ its edges. We denote the *closed neighborhood* of x by $N[x]$. Maximal cliques are denoted by the letters a to f , and vertices by the remaining letters. For $A \subseteq V(G)$, we denote by $G[A]$ the subgraph induced by A . Similarly, for $A \subseteq V(G')$, we denote by $\mathcal{R}'[A]$ the partial representations which only contains the pre-drawn intervals in A . By $P_{x,y}$ we denote an induced path from x to y ; its length is the number of edges.

For an interval $\langle x \rangle$, we denote its left endpoint by $\ell(x)$ and its right endpoint by $r(x)$. If $r(x) < \ell(y)$, we say that $\langle x \rangle$ is *on the left* of $\langle y \rangle$ and $\langle y \rangle$ is *on the right* of $\langle x \rangle$. We say that $\langle y \rangle$ is *between* $\langle x \rangle$ and $\langle z \rangle$ if $\langle x \rangle$ is on the left of $\langle y \rangle$ and $\langle z \rangle$ is on the right of $\langle y \rangle$, or vice versa. We also work with open intervals, for which the inequalities are non-strict.

We conclude with a list of the remaining notation. In Section 3, we define MPQ-trees, $s(N)$, $s_i(Q)$, $s_u^{\leftarrow}(Q)$, $s_u^{\rightarrow}(Q)$, $G[T]$, $G[N]$, $T[N]$, and Q -monotone paths. In Section 4, we define $\curvearrowright(a)$, $\curvearrowleft(a)$, I_a , \triangleleft , the flip operation, $P^{\mapsto}(a)$, and $P^{\leftarrow}(a)$.

2 Definition of Minimal Obstructions

In this section, we formally define all twelve classes of minimal obstructions which make a partial representation non-extendible.

Definition. Every *obstruction* consists of a graph H and a non-extendible partial representation \mathcal{R}'_H . This obstruction is *contained* in G and \mathcal{R}' if (i) H is an induced subgraph of G , (ii) the pre-drawn vertices of H are mapped to pre-drawn vertices of G , and (iii) the endpoints in \mathcal{R}'_H have the same left-to-right order as the endpoints of the corresponding pre-drawn vertices in \mathcal{R}' . For instance, the partial representation in Fig. 1b contains a 1-FAT obstruction, given in Fig. 3a.

We give H by *descriptions* using finitely many vertices, edges, and induced paths. For inner vertices of the induced paths, we specify their adjacencies with

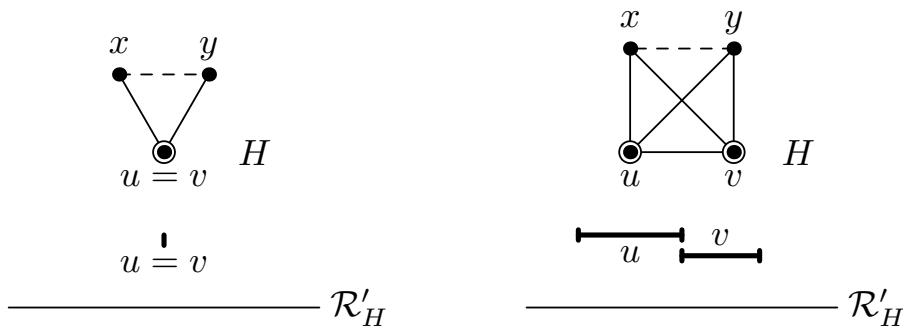


Fig. 4. The SE obstructions, on the left with $u = v$, on the right with $u \neq v$.

the remainder of H . Since these induced paths do not have fixed lengths, each description having at least one induced path defines an infinite class of forbidden subgraphs H . Unlike LB obstructions, most classes of minimal obstructions need infinitely many different descriptions. For instance, each FAT obstruction has k induced paths, and different values of k need different descriptions.

If H contains an induced path $P_{x,y}$, and x and y are allowed to be adjacent, then $P_{x,y}$ can be a single edge. When $N[x] = N[y]$, we allow the length of $P_{x,y}$ to be zero, i.e., $x = y$.

Minimality. An obstruction is *minimal* if \mathcal{R}'_H becomes extendible when any vertex is removed or any pre-drawn interval is made *free* by removing it from the partial representation \mathcal{R}'_H .

2.1 List of Minimal Obstructions

In Fig. 2, we have already described minimal LB obstructions of [26] with $\mathcal{R}'_H = \emptyset$. There are eleven other other classes of minimal obstructions we describe now.

SE obstructions. We start with two simple *shared endpoint obstructions* which deal with shared endpoints in \mathcal{R}' ; see Fig. 4. We have two pre-drawn vertices u and v such that $r(u) = \ell(v)$ (possibly $u = v$, so only one interval may be pre-drawn). Further, there are two non-adjacent vertices x and y , both adjacent to u and v . If $u \neq v$, the minimality requires that $\ell(u) < \ell(v) = r(u) < r(v)$.

k-FAT obstructions. The class of *forced asteroidal triple obstructions* is defined inductively; the first two obstructions 1-FAT and 2-FAT are depicted in Fig. 3a and b, respectively.

A 1-FAT obstruction consists of three pre-drawn non-adjacent vertices x_1 , y_1 and z_1 such that $\langle y_1 \rangle'$ is between $\langle x_1 \rangle'$ and $\langle z_1 \rangle'$. Further, x_1 and z_1 are connected by an induced path P_1 and y_1 is non-adjacent to the inner vertices of P_1 . See Fig. 3a.

A k -FAT obstruction is defined as follows; see Fig. 5a. Let H_{k-1} be the graph of a $(k-1)$ -FAT obstruction. To get H_k , we add to H_{k-1} two vertices x_k and t_k connected by an induced path P_k . Concerning edges, t_k is adjacent to all vertices of H_{k-1} , except for x_{k-1} . All vertices of H_{k-1} are non-adjacent to x_k and to the inner vertices of P_k . Further, for $k > 1$, we allow P_1 to be a single edge, so x_1 can be adjacent to z_1 .

We put $y_k = z_{k-1}$ and $z_k = y_{k-1}$. A k -FAT obstruction has three pre-drawn vertices x_k , y_k and z_k such that $\langle y_k \rangle'$ is between $\langle x_k \rangle'$ and $\langle z_k \rangle'$. The role of $\langle x_k \rangle'$, P_k and t_k is to force $\langle x_{k-1} \rangle'$ to be placed on the other side of $\langle z_k \rangle' = \langle y_{k-1} \rangle'$ than $\langle y_k \rangle' = \langle z_{k-1} \rangle'$, thus forcing the $(k-1)$ -FAT obstruction of H_{k-1} ; see Fig. 5b. The global structure forced by a k -FAT obstruction is depicted in Fig. 5c.

The remaining nine classes, depicted in Fig. 6, are derived from k -FAT obstructions. Let H_k denote the graph of a k -FAT obstruction. With exception of the last class of (k, ℓ) -CE obstructions, we create the graphs \tilde{H}_k of these obstructions by adding a few vertices to H_k . For $k = 1$, when one of x_1 and z_1

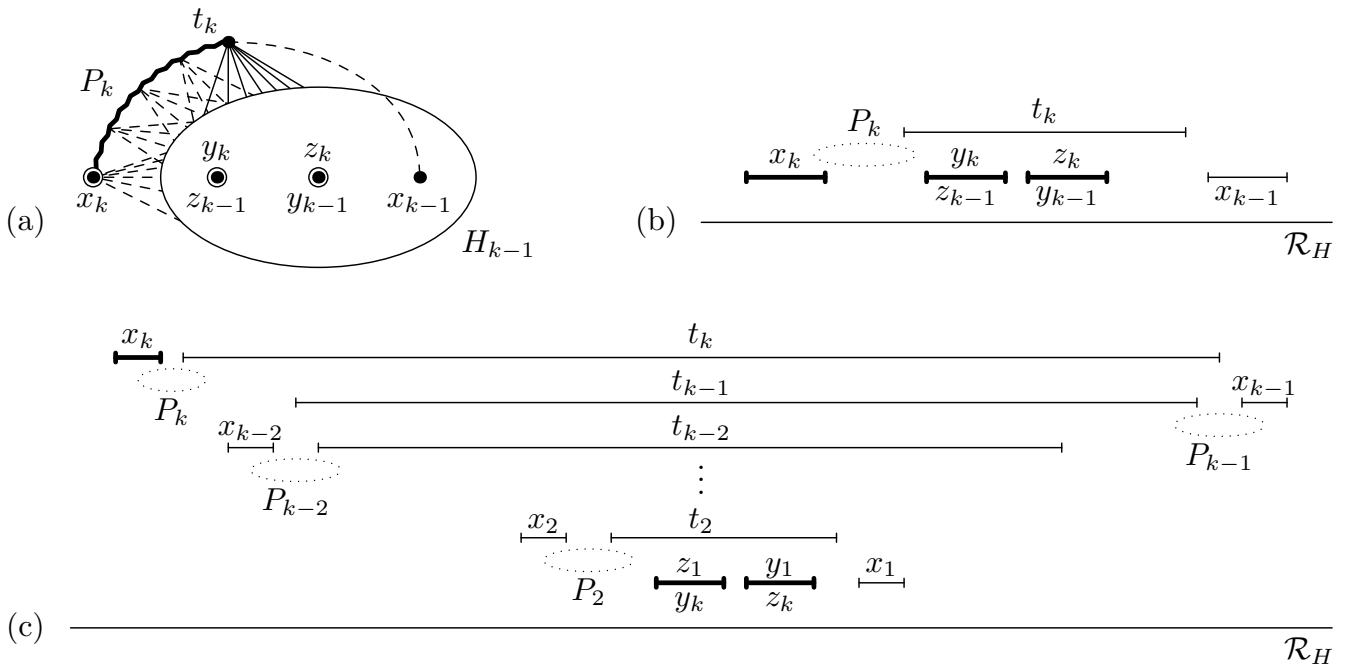


Fig. 5. (a) A k -FAT obstruction is created from a $(k-1)$ -FAT obstruction. It consists of the vertices $x_1, \dots, x_k, t_2, \dots, t_k, y_k, z_k$, and the induced paths P_1, \dots, P_k . The adjacencies are defined inductively.

(b) In every representation \mathcal{R}_H , the pre-drawn interval $\langle x_k \rangle'$ together with P_k and t_k forces $\langle x_{k-1} \rangle'$ to be placed on the right of $\langle z_k \rangle'$. Therefore, the induced $(k-1)$ -FAT obstruction is forced.

(c) The global zig-zag pattern forced by a k -FAT obstruction, with k nested levels going across $\langle y_k \rangle'$ and $\langle z_k \rangle'$. It is an obstruction since P_1 going from x_1 to z_1 with all inner vertices non-adjacent to y_1 cannot be placed.

is not pre-drawn, we also allow x_1 to be adjacent to z_1 . We also consider all of these obstructions horizontally flipped.

It is possible that the added vertices already belong to H_k ; for instance, a k -BI obstruction may have $u = t_k$ or $v = t_k$. Also, we do not specify in details the edges between the added vertices and $H_k \setminus \{x_k, y_k, z_k\}$. An accurate description would be too lengthy and the reader may derive it from Fig. 5c. We describe all minimal (k, ℓ) -CE obstructions in details.

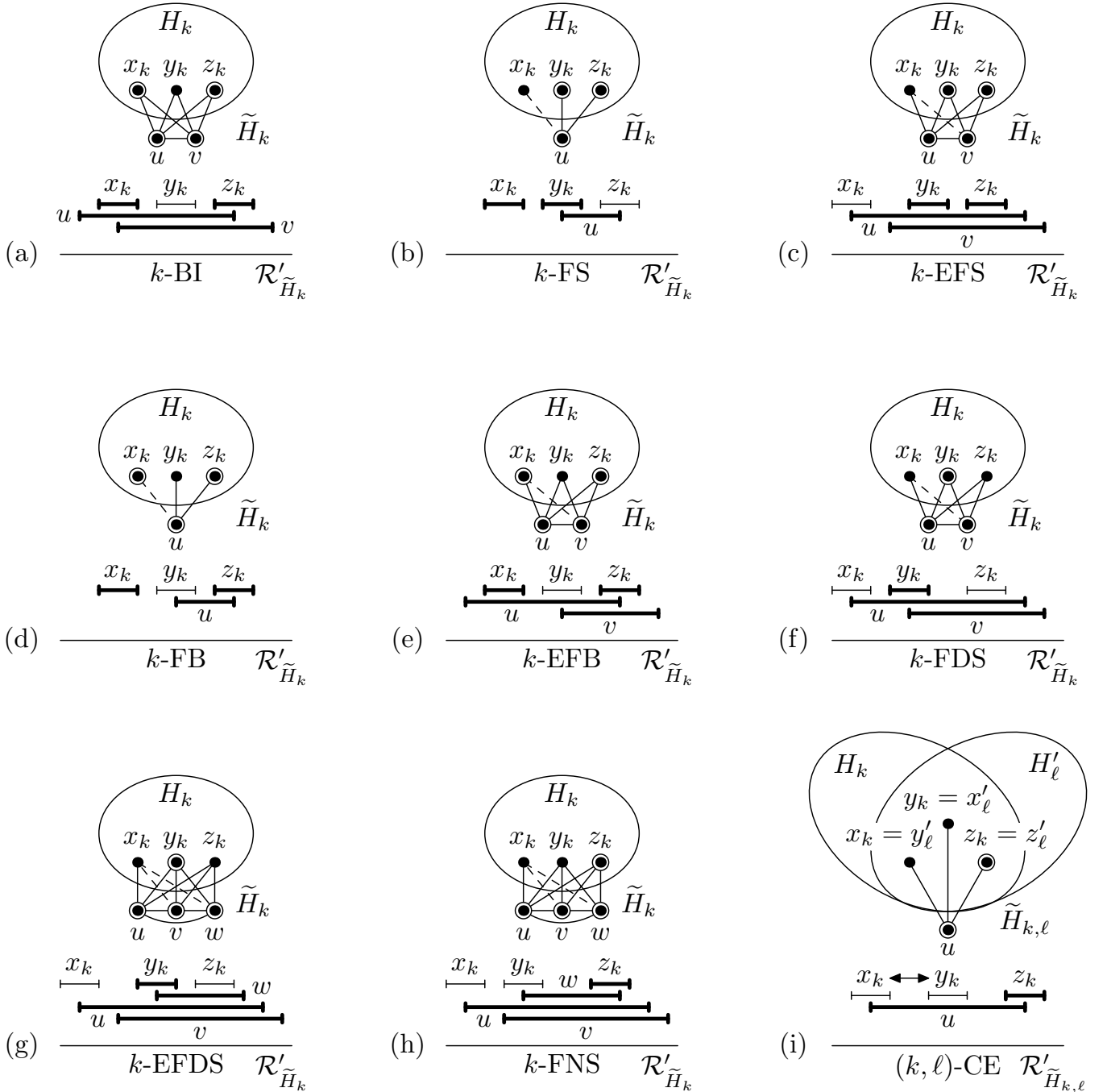


Fig. 6. Nine classes of obstructions derived from k -FAT obstructions.

k -BI obstructions. The class of *blocked intersection obstructions* is shown in Fig. 6a. To create \tilde{H}_k from H_k , we add two vertices u and v adjacent to x_k , y_k and z_k . Then the partial representation contains four pre-drawn vertices x_k , z_k , u and v . We have $\ell(u) \leq \ell(v) < r(u) \leq r(v)$, $\langle x_k \rangle'$ covering $\ell(v)$, and $\langle z_k \rangle'$ covering $r(u)$. We allow $u = v$.

The minimality further implies that $k \leq 2$. Indeed, a k -BI obstruction with $k > 3$ contains a smaller $(k, 1)$ -CE obstruction by removing v and freeing $\langle x_k \rangle'$ (this follows from Lemma 8.4). Concerning 1-BI, we allow $x_1 = z_1$. We illustrate all possible cases only for 1-BI obstructions, so the reader can understand the complexity of these classes; see Fig. 7. For $k = 2$, we know by Lemma 8.4 that x_2 is adjacent to t_2 . The pre-drawn intervals are as follows:

$$\begin{aligned} \ell(x_2) \leq \ell(u) \leq r(x_2) < \ell(z_2) \leq r(u) \leq r(z_2), & \quad \text{for } u = v, \\ \ell(u) < \ell(x_2) \leq \ell(v) \leq r(x_2) < \ell(z_2) \leq r(u) \leq r(z_2) < r(v), & \quad \text{for } u \neq v. \end{aligned}$$

The position of $\langle u \rangle'$ and $\langle v \rangle'$ forces $\langle y_2 \rangle'$ to be placed between $\langle x_2 \rangle'$ and $\langle y_2 \rangle'$ in every extending representation, which forces a 2-FAT obstruction.

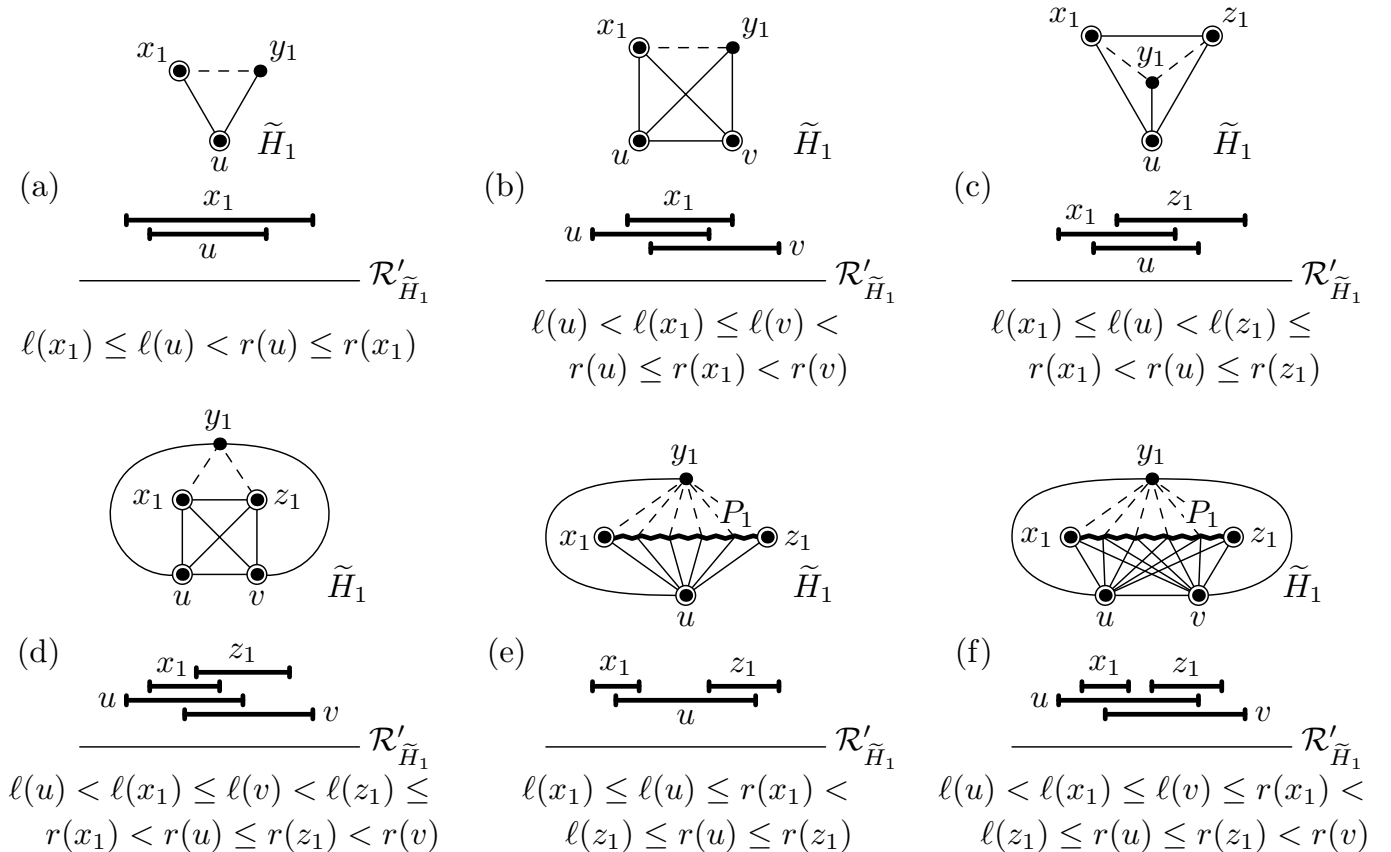


Fig. 7. All minimal 1-BI obstructions are depicted. Each gives several 1-BI obstructions with different $\mathcal{R}'_{\tilde{H}_1}$, since there are several possible orderings of the endpoints satisfying the given inequalities. We have $x_1 = z_1$ for (a) and (b), and $x_1 \neq z_1$ otherwise. We have $u = v$ for (a), (c) and (e), and $u \neq v$ otherwise.

k -FS obstructions. The class of *forced side obstructions* is shown in Fig. 6b. To create \tilde{H}_k from H_k , we add a vertex u adjacent to y_k and z_k . The partial representation contains three pre-drawn vertices x_k , y_k and u . We have $\ell(y_k) \leq \ell(u) \leq r(y_k) < r(u)$ and $\langle x_k \rangle'$ is on the left of $\langle y_k \rangle'$.

k -EFS obstructions. The class of *extended forced side obstructions* is similar to k -FS obstructions; see Fig. 6c. To create \tilde{H}_k from H_k , we add u adjacent to x_k , y_k , and z_k , and v adjacent to y_k and z_k . The partial representation contains four pre-drawn vertices y_k , z_k , u and v pre-drawn as follows:

$$\ell(u) < \ell(v) < \ell(y_k) \leq r(y_k) < \ell(z_k) \leq r(z_k) < r(u) \leq r(v).$$

k -FB obstructions. The class of *forced betweenness obstructions* is similar to k -BI with $u = v$; see Fig. 6d. To create \tilde{H}_k from H_k , we add u adjacent to y_k and z_k . The partial representation $\mathcal{R}'_{\tilde{H}_k}$ contains three pre-drawn vertices x_k , z_k , and u . We have $\ell(u) < \ell(z_k) \leq r(u) \leq r(z_k)$ and $\langle x_k \rangle'$ is pre-drawn on the left of $\langle u \rangle'$.

k -EFB obstructions. The class of *extended forced betweenness obstructions* is similar to both k -BI and k -FB; see Fig. 6e. To create \tilde{H}_k from H_k , we add u adjacent to x_k , y_k and z_k , and v adjacent to y_k and z_k . The partial representation contains four pre-drawn vertices x_k , z_k , u , and v . We have

$$\ell(u) < \ell(x_k) \leq r(x_k) < \ell(v) < \ell(z_k) \leq r(u) \leq r(z_k) < r(v).$$

k -FDS obstructions. The class of *forced different sides obstructions* is shown in Fig. 6f. To create \tilde{H}_k from H_k , we add u adjacent to x_k , y_k , and z_k , and v adjacent to y_k and z_k . The partial representation contains three pre-drawn vertices y_k , u and v pre-drawn as follows:

$$\ell(u) < \ell(y_k) \leq \ell(v) \leq r(y_k) < r(u) \leq r(v).$$

k -EFDS obstructions. The class of *extended forced different sides obstructions* is similar to k -FDS obstructions; see Fig. 6g. To the construction of k -FDS, we further add w adjacent to y_k and z_k . The partial representation contains four pre-drawn vertices y_k , u , v and w as follows:

$$\ell(u) < \ell(v) < \ell(y_k) \leq \ell(w) \leq r(y_k) < r(w) < r(u) \leq r(v).$$

k -FNS obstructions. The class of *forced nested side obstructions* is constructed similarly as k -EFDS obstructions, but with z_k pre-drawn instead of y_k ; see Fig. 6h. In $\mathcal{R}'_{\tilde{H}_k}$, we have

$$\ell(u) < \{\ell(v), \ell(w)\} \leq \ell(z_k) \leq r(w) < r(u) \leq r(v),$$

where $\ell(v)$ and $\ell(w)$ are ordered arbitrarily.

(k, ℓ) -CE obstructions. The class of *covered endpoint obstructions* is created from a k -FAT obstruction glued to an ℓ -FAT obstruction; see Fig. 6i. To create $\tilde{H}_{k,\ell}$, we glue H_k with H'_ℓ . We put $z_k = z'_\ell$, $x_k = y'_\ell$ and $y_k = x'_\ell$, and some other vertices of these obstructions may be also shared. We add u adjacent to x_k, y_k ,

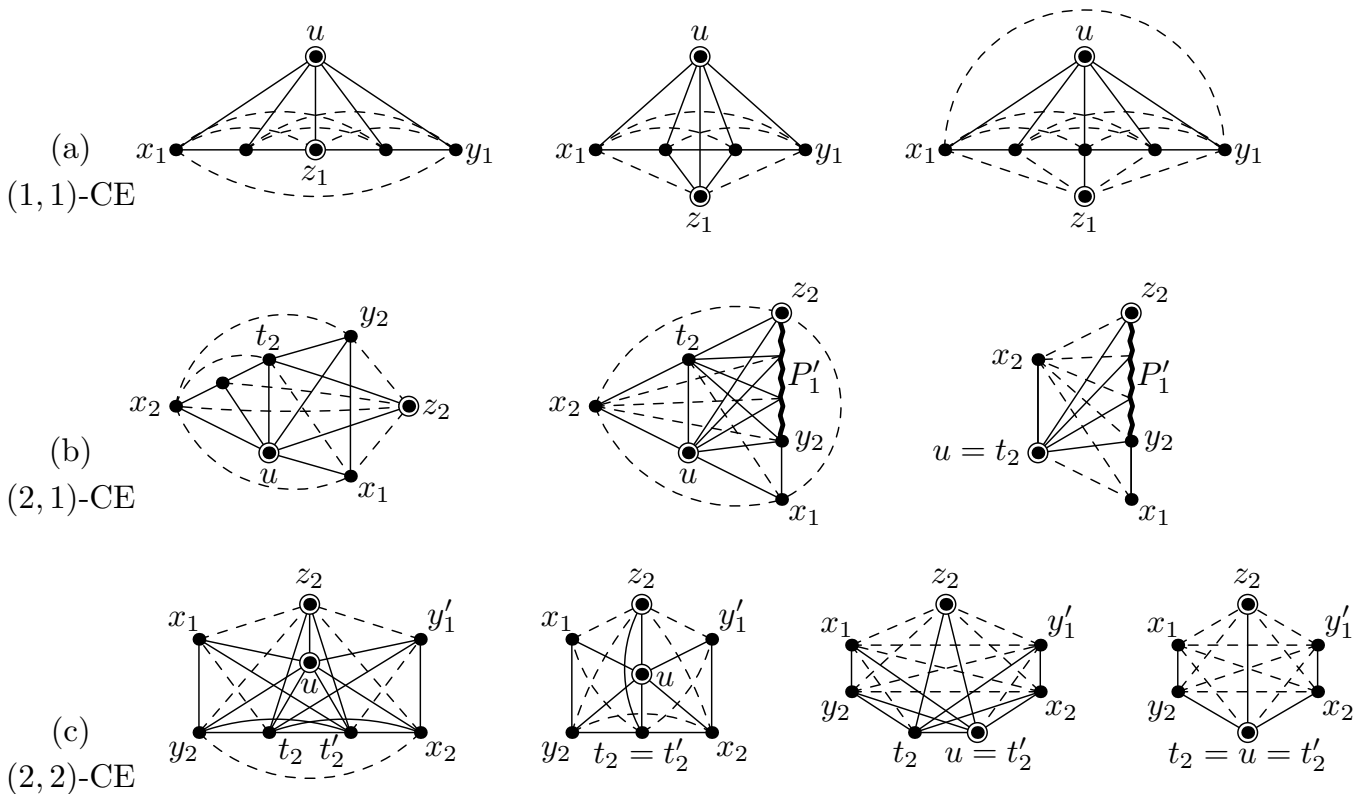


Fig. 8. (a) There are three minimal $(1, 1)$ -CE obstructions, and they are all finite graphs. The reason is that if, say, a path P_1 was very long, we could replace x_1 by an inner vertex of P_1 ; so such an obstruction would not be minimal.

(b) There are three minimal $(2, 1)$ -CE obstructions. Due to the minimality, P_2 is a path of length at most two. When x_2 and t_2 are non-adjacent, then $P'_1 = y_2 t_2 z_2$ is a path avoiding $N[x_2]$. When x_2 and t_2 are adjacent, there are two cases, namely, $u \neq t_2$, and $u = t_2$. The path P'_1 is of length at least two.

(c) There are four minimal $(2, 2)$ -CE obstructions, and they are all finite graphs. Necessarily $x_2 t_2$ and $y_2 t'_2$ are edges, and we can choose x_2 in such a way that it is adjacent to y'_1 (similarly, y_2 is adjacent to x_1). There are four different graphs, because the vertices u, t_2 and t'_2 might be distinct or not.

and z_k . The partial representation contains two pre-drawn intervals $\langle z_k \rangle'$ and $\langle u \rangle'$ such that $\ell(u) < \ell(z_k) \leq r(u) \leq r(z_k)$. We always assume that $k \geq \ell$.

In (k, ℓ) -CE Lemma 8.5, we show that the only (k, ℓ) -CE obstructions which are minimal are $(k, 1)$ -CE obstructions and $(2, 2)$ -CE obstructions; so either $\ell = 1$, or $k = \ell = 2$. For $k \geq 3$, a minimal $(k, 1)$ -CE obstruction consists of the subgraph H_k of a k -FAT obstruction together with a vertex u , where u is either adjacent to all vertices of H_k , or $u = t_k$. The remaining (k, ℓ) -CE obstructions, where $2 \geq k \geq \ell$, are depicted in Fig. 8.

2.2 Proofs of Non-extendibility and Minimality

We sketch proofs that the defined obstructions are non-extendible and minimal. This implies the first part of Theorem 1.1. We establish the harder implication in Sections 5, 6, 7, 8, and 9.

Lemma 2.1. *Every k -FAT obstruction is non-extendible and minimal.*

Proof. We prove the claim by induction. For $k = 1$, non-extendibility and minimality are clear. For $k > 1$, assume that $\langle x_k \rangle'$ is on the left of $\langle y_k \rangle'$, and $\langle y_k \rangle'$ is on the left of $\langle z_k \rangle'$. In every representation of k -FAT, $\langle t_k \rangle$ covers $[\ell(y_k), \ell(z_k)]$. We know that $\langle x_{k-1} \rangle$ cannot be on the left of $\langle x_k \rangle'$, since H_{k-1} is connected and x_k is non-adjacent to all vertices of H_{k-1} . Therefore $\langle x_{k-1} \rangle$ has to be placed on the right of $\langle z_k \rangle'$. We get a $(k - 1)$ -FAT obstruction, which is non-extendible by the induction hypothesis.

It remains to argue the minimality. If one of $\langle x_k \rangle'$, $\langle y_k \rangle'$ and $\langle z_k \rangle'$ is made free, we can place them in such a way that $\langle z_k \rangle$ is between $\langle x_k \rangle$ and $\langle y_k \rangle$. This makes the partial representation extendible: It works for $k = 1$, and for $k > 1$, we can place x_{k-1} on the right of $\langle y_k \rangle$, which makes the induced H_{k-1} extendible. If we remove one of the vertices or induced paths, the argument is similar. \square

Lemma 2.2. *The following obstructions are non-extendible and minimal:*

- *SE, k -FS, k -EFS, k -FB, k -EFB, k -FDS, k -EFDS, and k -FNS obstructions,*
- *k -BI obstructions for $k \leq 2$,*
- *(k, ℓ) -CE obstructions where either $\ell = 1$, or $k = \ell = 2$.*

Proof. For SE obstructions, the proof is trivial. For the remaining classes (aside k -BI and (k, ℓ) -CE), we proceed as follows. Non-extendibility follows from the

fact that, in all cases, $\langle y_k \rangle$ is forced to be placed between $\langle x_k \rangle$ and $\langle z_k \rangle$. To show minimality, we use the minimality of k -FAT obstructions. Then it is easy to show that freeing any added pre-drawn interval or removing any added vertex results in the possibility of placing $\langle z_k \rangle$ between $\langle x_k \rangle$ and $\langle y_k \rangle$.

Consider a k -BI where $k \leq 2$. Non-extendibility follows from the fact that $\langle y_k \rangle$ has to be placed between $\langle x_k \rangle'$ and $\langle z_k \rangle'$, thus forcing the k -FAT obstruction, which is non-extendible by Lemma 2.1. By removing a vertex or an induced path of H_k , it becomes extendible as argued in Lemma 2.1. By freeing $\langle u \rangle'$ or $\langle z_k \rangle'$, we can place $\langle y_k \rangle$ on the right of $\langle z_k \rangle'$ which makes the partial representation extendible. By freeing $\langle v \rangle'$ or $\langle x_k \rangle'$, we can place $\langle y_k \rangle$ on the left of $\langle x_k \rangle'$, which also makes it extendible because $k \leq 2$ and x_2 is adjacent to t_2 .

For (k, ℓ) -CE, either $\langle y_k \rangle$ is between $\langle x_k \rangle$ and $\langle z_k \rangle'$ (non-extendible due to the k -FAT obstruction), or $\langle y_\ell \rangle$ is between $\langle x_\ell \rangle$ and $\langle z_\ell \rangle'$ (non-extendible due to the ℓ -FAT obstruction). Minimality is also easy: Removing or freeing u allows to place $\langle z_k \rangle'$ between $\langle x_k \rangle$ and $\langle y_k \rangle$, which is extendible. And removing anything from one of the FAT obstructions allows one of the orderings of $\langle x_k \rangle$ and $\langle y_k \rangle$ to be extendible. \square

We note that the list of minimal obstructions is unique. Indeed, every minimal obstruction itself corresponds to a valid input, which cannot be obstructed by a distinct obstruction due to the minimality. Therefore, it is not possible to construct a smaller list of minimal obstructions, or to argue that if the partial representation contains a particular obstruction, then it also contains an additional one.

3 Maximal Cliques and MPQ-trees

In this section, we review well-known properties of interval graphs. First, we describe their characterization in terms of orderings of maximal cliques. Then, we introduce two data structures to deal with these orderings, namely, PQ-trees and MPQ-trees. Finally, we prove some simple structural results concerning MPQ-trees.

Consecutive Orderings. Fulkerson and Gross [12] proved the following fundamental characterization of interval graphs:

Lemma 3.1 (Fulkerson and Gross [12]). *A graph is an interval graph if and only if there exists a linear ordering $<$ of its maximal cliques such that, for each vertex, the maximal cliques containing this vertex appear consecutively.*

We call an ordering of the maximal cliques satisfying the statement of Lemma 3.1 a *consecutive ordering*. See Fig. 9 for an example. The ordering $<$ from the statement is obtained by sweeping an interval representation from left to right. By the Helly property, the intervals of every maximal clique have a non-empty intersection. For all maximal cliques, these intersections are disjoint and ordered from left to right. In the intersection of the intervals of a maximal clique a , we pick one point which we call a *clique-point* $cp(a)$. The left-to-right ordering of these clique-points gives $<$. On the other hand, given a consecutive ordering $<$, we place the clique-points from left to right according to $<$ and construct an interval representation by placing each interval on top of its clique-points and no others. This can be done because the ordering places the maximal cliques containing each of the vertices consecutively.

PQ-trees. Booth and Lueker [5] designed a data structure called PQ-trees to efficiently work with consecutive orderings of maximal cliques. A *PQ-tree* T is a rooted tree. Its leaves are in one-to-one correspondence with the maximal cliques. Its inner nodes are of two types: *P-nodes* and *Q-nodes*. Each P-node

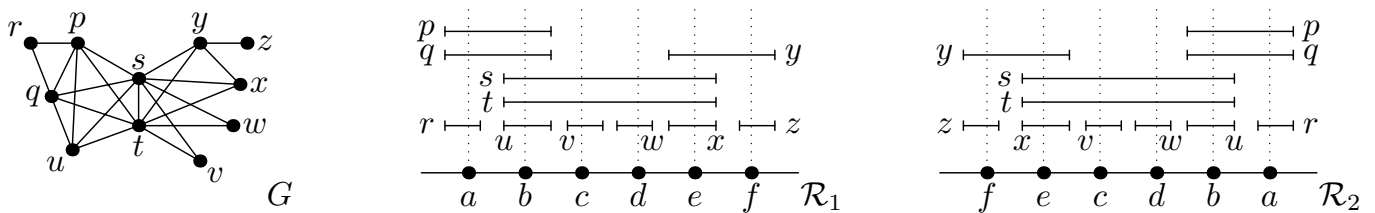


Fig. 9. An interval graph G and two of its representations with different left-to-right orderings $<$ of the maximal cliques. Some choices of clique-points are depicted on the real lines.

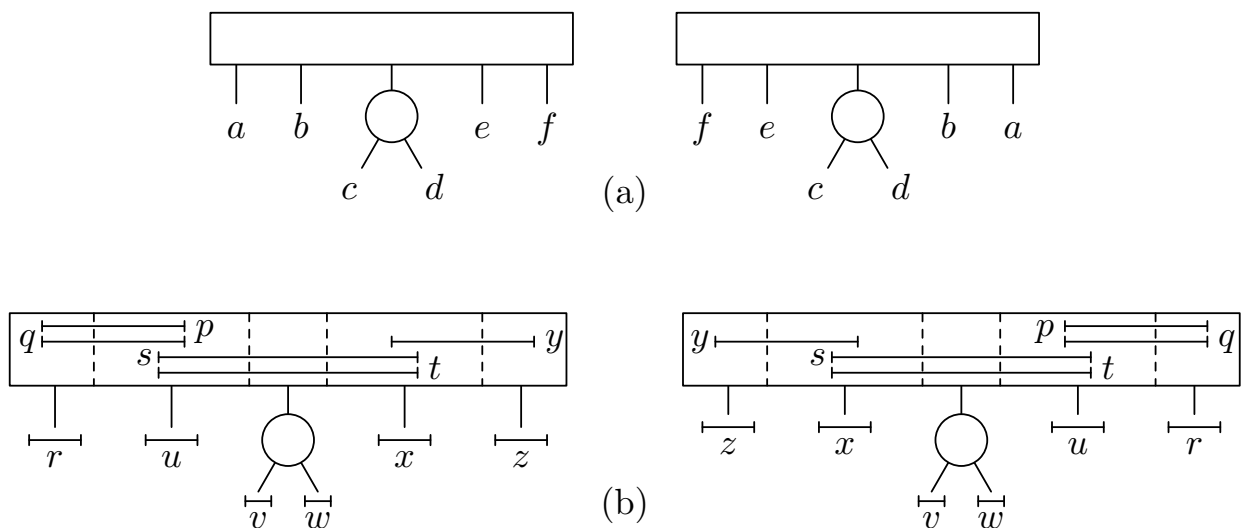


Fig. 10. (a) Two equivalent PQ-trees with frontiers $a < b < c < d < e < f$ and $f < e < c < d < b < a$, respectively. In all figures, we denote P-nodes by circles and Q-nodes by rectangles. (b) The corresponding MPQ-trees with depicted sections.

has at least two children, and each Q-node has at least three. Further, for every inner node, a left-to-right ordering of its children is given. Every PQ-tree T represents one linear ordering $<_T$ of the maximal cliques called the *frontier* of T , which is the ordering of the leaves from left to right.

Every PQ-tree T further represents other linear orderings. These orderings are frontiers of equivalent PQ-trees. A PQ-tree T' is *equivalent* to T if it can be constructed from T by a sequence of *equivalent transformations* of two types: (i) an arbitrary reordering of the children of a P-node, and (ii) a reversal of the order of the children of a Q-node. Fig. 10a depicts two equivalent PQ-trees corresponding to the interval graph from Fig. 9.

Booth and Lueker proved that, for every interval graph, there exists a unique PQ-tree (up to equivalence transformations) representing precisely the consecutive orderings of the maximal cliques. In other words, this tree describes all possible interval representations of this interval graph.

A subtree of T consists of a node and all its descendants. The subtrees of a node N are those subtrees having the children of N as the roots. For a node N , let $T[N]$ denote the subtree of T with the root N .

MPQ-trees. For the purpose of this paper, we need more information about the way in which the vertices of the interval graph are related to the structure of the PQ-tree. This additional information is contained in the *modified PQ-tree* (MPQ-tree), introduced by Korte and Möhring [25]. We note that the same idea is already present in the earlier paper of Colbourn and Booth [8].

The MPQ-tree is an augmentation of the PQ-tree in which the nodes of T have assigned subsets of $V(G)$ called *sections*. To a leaf representing a clique a , we assign one section $s(a)$. Similarly, to each P-node P , we assign one section $s(P)$. For a Q-node Q with n children, we have n sections $s_1(Q), \dots, s_n(Q)$, each corresponding to one subtree of Q .

The section $s(a)$ has all vertices contained in the maximal clique a and no other maximal clique. The section $s(P)$ of a P-node P has all vertices that are contained in all maximal cliques of $T[P]$ and in no other maximal clique. Sections of Q-nodes are more complicated. Let Q be a Q-node with subtrees T_1, \dots, T_n . Let x be a vertex contained only in maximal cliques of $T[Q]$, and suppose that it is contained in maximal cliques of at least two subtrees. Then x is contained in every section $s_i(Q)$ such that some maximal clique of T_i contains x . Fig. 10b depicts the sections for the example in Fig. 9.

Korte and Möhring [25] state the following properties:

- Every vertex x is placed in the sections of exactly one node of T . In the case of a Q-node, it is placed in consecutive sections of this node.
- For a Q-node Q , if x is placed in a section $s_i(Q)$, then x is contained in all cliques of T_i .
- Every section of a Q-node is non-empty. Moreover, two consecutive sections have a non-empty intersection.
- A maximal clique contains exactly those vertices contained in the sections encountered when we traverse the tree from the corresponding leaf to the root.

Structure of MPQ-trees. Next, we show several structural properties used in building minimal obstructions which are quite easy to prove:

Lemma 3.2. *Let Q be a Q-node. Then $s_i(Q) \neq s_j(Q)$ for every $i \neq j$. Further, if $s_i(Q) \subsetneq s_{i+1}(Q)$, then at least one section of T_i is non-empty.*

Proof. If $s_i(Q) = s_j(Q)$, then we could exchange T_i and T_j and we would obtain a valid MPQ-tree for G . Since $n \geq 3$, this yields a contradiction with the fact that the only possible transformation of a Q-node is reverting the order of its children.

For the latter part, let a and b respectively be maximal cliques of a leaf in T_i and a leaf in T_{i+1} . Then $a \setminus b \neq \emptyset$ and every $x \in a \setminus b$ belongs to sections of T_i . □

Let N be a node of the MPQ-tree. By $G[N]$ we denote the subgraph induced by all the vertices in the sections of the subtree rooted at N . Similarly, for a subtree T' , we denote the subgraph induced by the vertices in its sections by $G[T']$.

Lemma 3.3. *Let N be an inner node of an MPQ-tree.*

- (i) *If N is a Q-node, then $G[N]$ is connected.*
- (ii) *If N is a P-node, then $G[N]$ is connected if and only if $s(N)$ is non-empty. Furthermore, for every child T_i of N , the graph $G[T_i]$ is connected.*

Proof. (i) It follows from the facts that the vertices in any section form a clique, and that any two consecutive sections of N have non-empty intersection.

(ii) The first statement is clear. For the second part, notice that if $G[T_i]$ was not connected, we could permute the connected components of $G[T_i]$ arbitrarily with the other children of N . Therefore T_i would not be a child of N , but N would have one child per each connected component of $G[T_i]$. □

Let Q be a Q-node and $i < j$. Let x and y be two vertices of $G[Q]$, where x is either in T_i , or $s_i(Q)$, and y is either in T_j , or $s_j(Q)$. A path $P_{x,y}$ is called *Q-monotone* if all inner vertices of the path belong to the sections of Q , and their leftmost/rightmost sections strictly increase.

Lemma 3.4. *Let H be an induced subgraph of $G[Q]$ such that $x, y \in V(H)$ belong to one component. Then every shortest path $P_{x,y}$ in H is Q-monotone.*

Proof. It is easy to see that any path from x to y that is not Q-monotone can be shortened. \square

Let Q be a Q-node. Let u be a vertex appearing in sections of $T[Q]$. If u belongs to sections of Q , let $s_u^{\leftarrow}(Q)$ be the leftmost section of Q containing u and $s_u^{\rightarrow}(Q)$ be the rightmost one. If u belongs to sections of a subtree T_i of Q , we put $s_u^{\leftarrow}(Q) = s_u^{\rightarrow}(Q) = s_i(Q)$. If $s_u^{\rightarrow}(Q)$ is on the left of $s_v^{\leftarrow}(Q)$, then we say that u is on the left of v and v is on the right of u . Also, u and v are on the same side of w if they are both on the left of w , or both on the right of w . Similarly, v is between u and w if either u is on the left and w is on the right of v , or u is on the right and w is on the left of v . For a maximal clique $a \in T_i$, we say that u is on the left of a when $s_u^{\rightarrow}(Q)$ is on the left of $s_i(Q)$, and similarly the other relations.

Non-adjacencies of Maximal Cliques. Maximal cliques of interval graphs have the following special property, which we use to build minimal obstructions.

Lemma 3.5. *Let H be a connected subgraph of an interval graph and let c be a maximal clique with no vertex in $V(H)$. There exists $x \in c$ non-adjacent to all vertices of $V(H)$.*

Proof. Consider an interval representation \mathcal{R} . It places all intervals of H to one side of $\text{cp}(c)$, say on the left. Let x be the interval of c having the rightmost left endpoint. If x is adjacent to some vertex $y \in V(H)$, then every vertex of c is adjacent to y . Since c is maximal, it follows that $y \in c$, contradicting the assumption. So x is non-adjacent to all vertices of $V(H)$. \square

4 Characterizing Extendible Partial Representations by Maximal Cliques

In this section, we explain the characterization of extendible partial representations due to Klavík et al. [21].

Restricting Clique-points. Suppose that there exists a representation \mathcal{R} extending \mathcal{R}' . Then \mathcal{R} gives some consecutive ordering $<$ of the maximal cliques from left to right. We want to show that the pre-drawn intervals give constraints in the form of a partial ordering \triangleleft . Fig. 11 illustrates these constraints given by a pair of pre-drawn intervals. By generalizing it to all pre-drawn intervals, we get the partial ordering \triangleleft .

For a maximal clique a , let $P(a)$ denote the set of all pre-drawn intervals that are contained in a . Recall that a clique-point $\text{cp}(a)$ is some point chosen from the intersection of all intervals of a in the representation \mathcal{R} . Then $P(a)$ restricts the possible position of the clique-point $\text{cp}(a)$ to only those points x of the real line which are covered in \mathcal{R}' by the pre-drawn intervals of $P(a)$ and no others. We denote the set of these admissible positions by \downarrow_a . Formally:

$$\downarrow_a = \{x : x \in \mathbb{R} \text{ and } x \in \langle u \rangle' \iff u \in P(a)\};$$

for examples see Fig. 12a. Equivalently, \downarrow_a is defined in [2] as

$$\downarrow_a = \left(\bigcap_{u \in P(a)} \langle u \rangle' \right) \setminus \left(\bigcup_{v \notin P(a)} \langle v \rangle' \right). \quad (1)$$

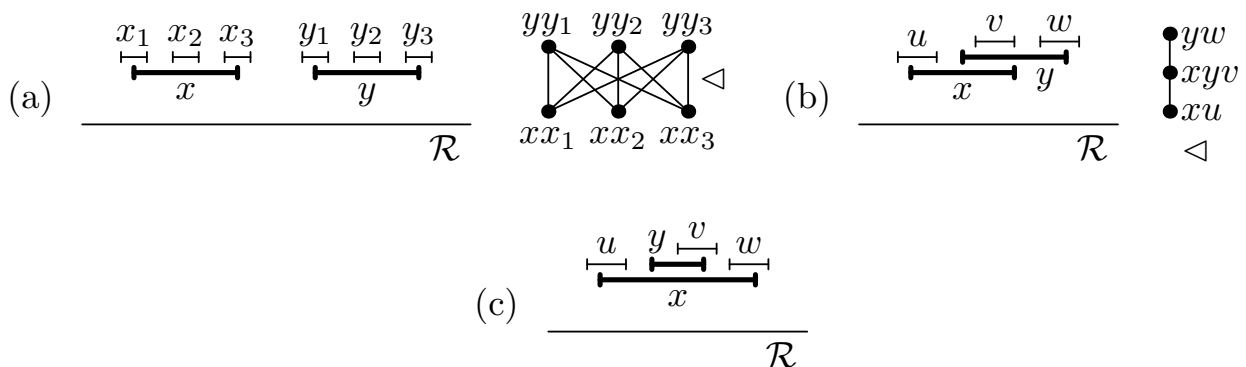


Fig. 11. Possible relative positions of pre-drawn intervals $\langle x \rangle'$ and $\langle y \rangle'$, and some examples of the Hasse diagrams of the posed constraints. The consecutive ordering of the maximal cliques of every extending representation has to extend \triangleleft . (a) All maximal cliques containing x have to be on the left of those containing y . (b) All maximal cliques containing x have to be on the left of those containing both x and y , which are on the left of those containing only y . (c) An inclusion of pre-drawn intervals poses no constraints. A maximal clique containing only x can be either on the left, or on the right of the maximal cliques containing both x and y .

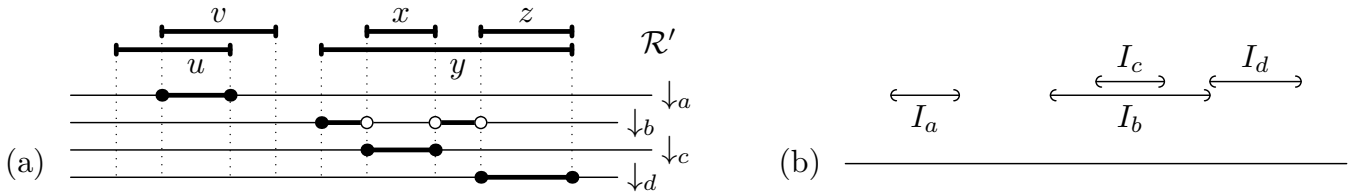


Fig. 12. (a) Four maximal cliques a , b , c , and d with $P(a) = \{u, v\}$, $P(b) = \{y\}$, $P(c) = \{x, y\}$, and $P(d) = \{y, z\}$. The possible positions \downarrow_a , \downarrow_b , \downarrow_c , and \downarrow_d of their clique-points are illustrated. (b) The corresponding open intervals I_a , I_b , I_c , and I_d .

We are interested in the extremal points of \downarrow_a . By $\smile(a)$ (resp. $\frown(a)$), we denote the infimum (resp. the supremum) of \downarrow_a . We use an open interval $I_a = (\smile(a), \frown(a))$ to represent \downarrow_a . We note that this does not imply that \downarrow_a contains all points between $\smile(a)$ and $\frown(a)$; see \downarrow_b in Fig. 12. Notice that when $P(a) = \emptyset$, then $I_a = \mathbb{R}$.

The Interval Order \triangleleft . For two distinct maximal cliques a and b , we write $a \triangleleft b$ if $\frown(a) \leq \smile(b)$, or in other words, if I_a is on the left of I_b . We put $a \triangleleft a$ when $\downarrow_a = \emptyset$. The definition of \triangleleft is quite natural, since $a \triangleleft b$ implies that every extending representation \mathcal{R} has to place $\text{cp}(a)$ to the left of $\text{cp}(b)$. For instance, in Fig. 12, we get that $a \triangleleft b \triangleleft d$ and $a \triangleleft c \triangleleft d$, but b and c are incomparable.

We note that the ordering \triangleleft is a so-called *interval order* represented by open intervals I_a . The reason is that $a \triangleleft b$ if and only if I_a and I_b are disjoint and I_a is on the left of I_b . Interval orders are studied in the context of time constraints and have many applications; for instance, see [11].

Lemma 4.1 (Klavík et al. [21]). *A partial representation \mathcal{R}' is extendible if and only if there exists a consecutive ordering of the maximal cliques that extends \triangleleft .*

It is obvious that the constraints posed by \triangleleft are necessary. The other implication is proved in [21] as follows. Suppose that $<$ is a consecutive ordering extending \triangleleft . We place the clique-points greedily from left to right according to $<$. We place each clique-point on the right of the previously placed ones, as far to the left as possible. It is shown that if this greedy procedure fails, then either $<$ does not extend \triangleleft , or it is not a consecutive ordering. See Appendix A for details.

Overlaps. In this paper, we show one additional crucial property of \triangleleft . We say that a pair of intervals I_a and I_b *single overlaps* if $I_a \neq I_b$ and either $\smile(a) \leq \smile(b) < \frown(a) \leq \frown(b)$, or $\smile(b) \leq \smile(a) < \frown(b) \leq \frown(a)$.

Lemma 4.2. *No pair of intervals I_a and I_b single overlaps.*

Proof. Assume without loss of generality that $\curvearrowright(a) \leq \curvearrowright(b)$. If $\curvearrowright(a) \leq \curvearrowright(b)$, then I_a and I_b are disjoint and do not single overlap. Suppose now that $\curvearrowright(a) \leq \curvearrowright(b) < \curvearrowleft(a)$. Since all intervals of $P(a)$ cover $[\curvearrowright(a), \curvearrowleft(a)]$, we get $P(a) \subseteq P(b)$.

The position of $\curvearrowright(a)$ can be defined as a result of two distinct situations:

- If some pre-drawn interval of $P(a)$ ends in $\curvearrowright(a)$, then $\curvearrowright(b) \leq \curvearrowright(a)$, since the same pre-drawn interval is contained in $P(b)$.
- Otherwise, there exists a sequence of pre-drawn intervals not contained in $P(a)$ that covers the whole portion between $\curvearrowright(a)$ and the leftmost right endpoint of the intervals of $P(a)$. The left endpoints of these intervals are on or to the right of $\curvearrowright(a)$. Since the left endpoints of the intervals in $P(b)$ are to the left of $\curvearrowright(a)$, the pre-drawn intervals of the sequence are not contained in $P(b)$. Thus, $\curvearrowright(b) \leq \curvearrowright(a)$.

In both cases, $\curvearrowright(a) \leq \curvearrowright(b) \leq \curvearrowleft(b) \leq \curvearrowleft(a)$, so I_b is contained in I_a . \square

If no single overlaps are allowed, every pair of intervals is either disjoint, or one interval is contained in the other (possibly the intervals are equal). This type of interval orderings is very simple and has not been much studied. We note that graphs having interval representations with no single overlaps are called *trivially perfect*. By examining the above proof, we get the following useful result:

Lemma 4.3. *If $I_a \subseteq I_b$, then $P(a) \supseteq P(b)$. Further, strict containments correspond to strict inclusions.* \square

If I_a and I_b are disjoint, then we only know that at least one of the sets $P(a) \setminus P(b)$ and $P(b) \setminus P(a)$ is non-empty. They both might be non-empty, or the sets $P(a)$ and $P(b)$ might be in inclusion. See Fig. 12 for examples.

Sliding Lemma. We introduce some notation. We denote by $P^{\leftarrow}(a)$ and $P^{\rightarrow}(a)$ respectively the subsets of $P(a)$ containing the pre-drawn intervals with left-most right endpoints, and with right-most left endpoints. If $u \in P^{\leftarrow}(a)$ and $v \in P^{\rightarrow}(a)$, then $\langle u \rangle' \cap \langle v \rangle' = \bigcap_{w \in P(a)} \langle w \rangle'$, thus I_a is a subinterval of $\langle u \rangle' \cap \langle v \rangle'$.

Single overlaps of pre-drawn intervals pose more constraints than containment (see Fig. 11b and c). Therefore, single overlaps are more powerful in building obstructions. The following lemma states that, under some assumptions, we can turn a containment of pre-drawn intervals into a single overlap of other pre-drawn intervals; see Fig. 13.

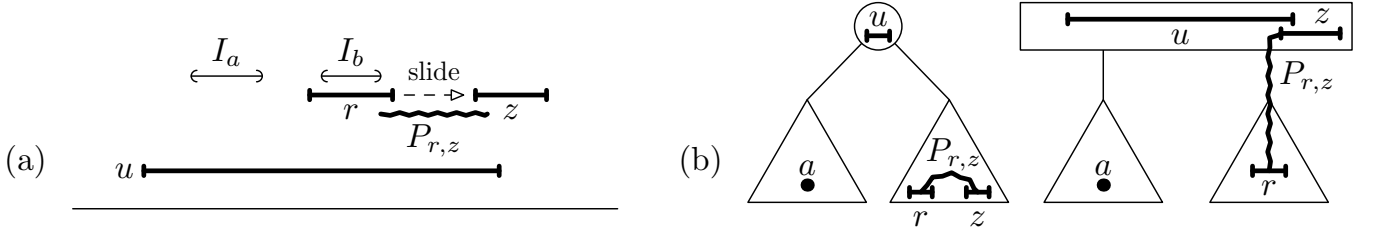


Fig. 13. (a) With the assumption satisfied, we can slide r to z which covers $r(u)$. (b) The relative positions in the MPQ-trees of z and r with respect to a are the same.

Lemma 4.4 (Sliding). *Let I_a be on the left of I_b , $P(a) \subsetneq P(b)$ and $r \in P(b) \setminus P(a)$.*

- (i) *There exists a pre-drawn interval $\langle z \rangle'$ on the right of I_a covering $r(u)$, for $u \in P^{\leftarrow}(a)$. Further, there exists an induced path $P_{r,z}$ from r to z whose vertices are all pre-drawn and not contained in $P(a)$.*
- (ii) *Consider the smallest subtree having a and the sections containing r . If the root of this subtree is a P -node, then z and r are contained in the same subtree. If the root is a Q -node, then z and r appear on the same side of a .*

Proof. (i) By the assumptions and the definition of I_a , we get that $(\curvearrowright(a), r(u)]$ is not empty and all points in $(\curvearrowright(a), r(u)]$ are covered by pre-drawn intervals not in $P(a)$. Among these intervals, we choose z covering $r(u)$. Since r is also one of these intervals, we can construct an induced path from r to z , consisting of pre-drawn intervals not in $P(a)$.

(ii) It follows from the existence of $P_{r,z}$ not contained in a . □

We note that possibly $r = z$. The above lemma is repeatedly used for constructing minimal obstructions. The general idea is the fact that $\langle r \rangle'$ properly contained inside $\langle u \rangle'$ restricts the partial representation less than $\langle z \rangle'$ covering $r(u)$. The lemma says that we can assume that such z exists and use it instead of r .

Flip Operation. We say that we *flip* the partial representation *vertically* when we map every $x \in \mathbb{R}$ to $-x$. This reverses the ordering \triangleleft . Clearly, there exists an obstruction in the original partial representation if and only if the flipped obstruction is present in the flipped partial representation. The purpose of this operation is to decrease the number of cases in the proofs.

5 Strategy for Finding Minimal Obstructions

In this section, we describe the general strategy to show that every non-extendible partial representation contains one of the obstructions described in Section 2.

For any two disjoint subtrees T_i and T_j of the MPQ-tree T , we write $T_i \triangleleft T_j$ if and only if there exist cliques $a \in T_i$ and $b \in T_j$ such that $a \triangleleft b$. In this situation, the maximal cliques of T_i are forced to appear on the left of the maximal cliques of T_j .

Testing Extendibility by MPQ-tree Reordering. Recall that a MPQ-tree T represents all feasible orderings of the maximal cliques of a given interval graph G . By Lemma 4.1, a partial representation is extendible if and only if there exists a reordering T' of T such that the frontier of T' extends \triangleleft . This condition can be tested by the following algorithm (see [21]).

We process the MPQ-tree T from the bottom to the root. When a P-node is processed, we test whether there exists a linear extension of \triangleleft on its subtrees. It exists if and only if \triangleleft induced on the subtrees of the node is acyclic. Thus, if there is a cycle, the MPQ-tree cannot be reordered according to \triangleleft . When a Q-node is processed, there are two possible orderings of its subtrees, and we

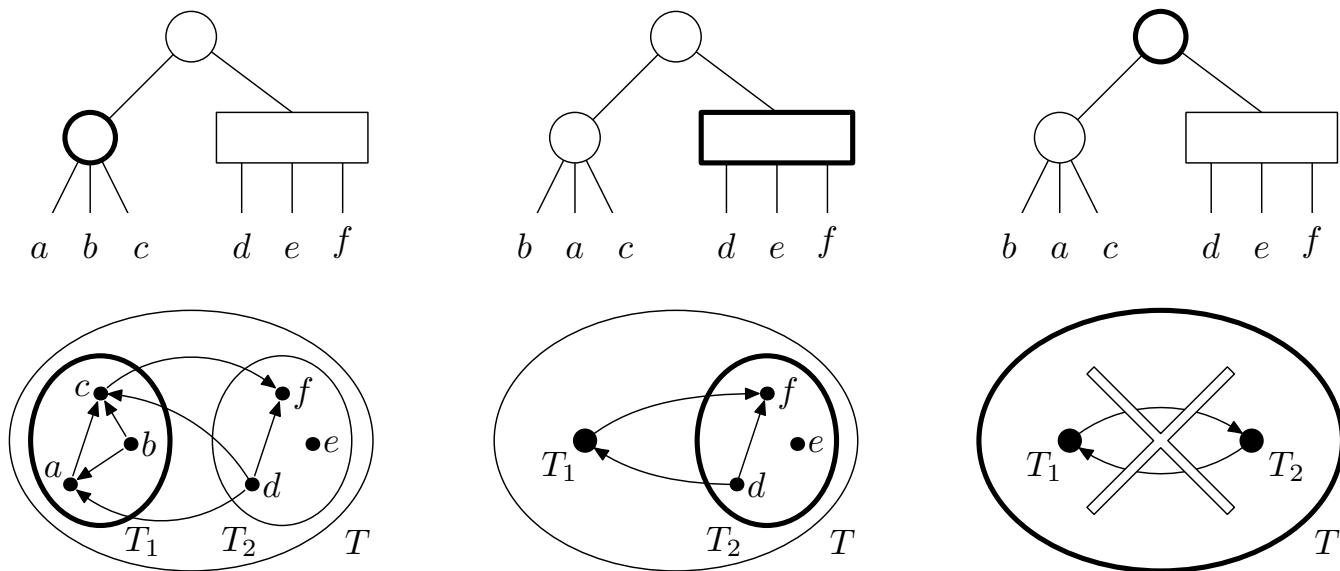


Fig. 14. This example is from [21], and it shows from left to right the way in which the reordering algorithm works. We depict comparable pairs of maximal cliques by directed edges. The processed trees are contracted into vertices.

First, we reorder the highlighted P-node on the left. The subdigraph induced by a, b and c is ordered $b \rightarrow a \rightarrow c$. We contract this subtree T_1 into a vertex. Next, we keep the order of the highlighted Q-node and contract its subtree T_2 into a vertex. When we reorder the root P-node, the algorithm finds a two-cycle between T_1 and T_2 , and outputs “no”.

check whether any of them is compatible with \triangleleft . The partial representation is extendible if and only if all nodes can be reordered in this manner. See Fig. 14 for an example.

A node that cannot be reordered is called *obstructed*. A set of maximal cliques *creates* an obstruction if the ordering of this set in \triangleleft makes the node obstructed.

Strategy. Suppose that a partial representation \mathcal{R}' is non-extendible. From [21], we know that there exists an obstructed node in the MPQ-tree. We divide the argument into three cases, according to the type of this node: *an*

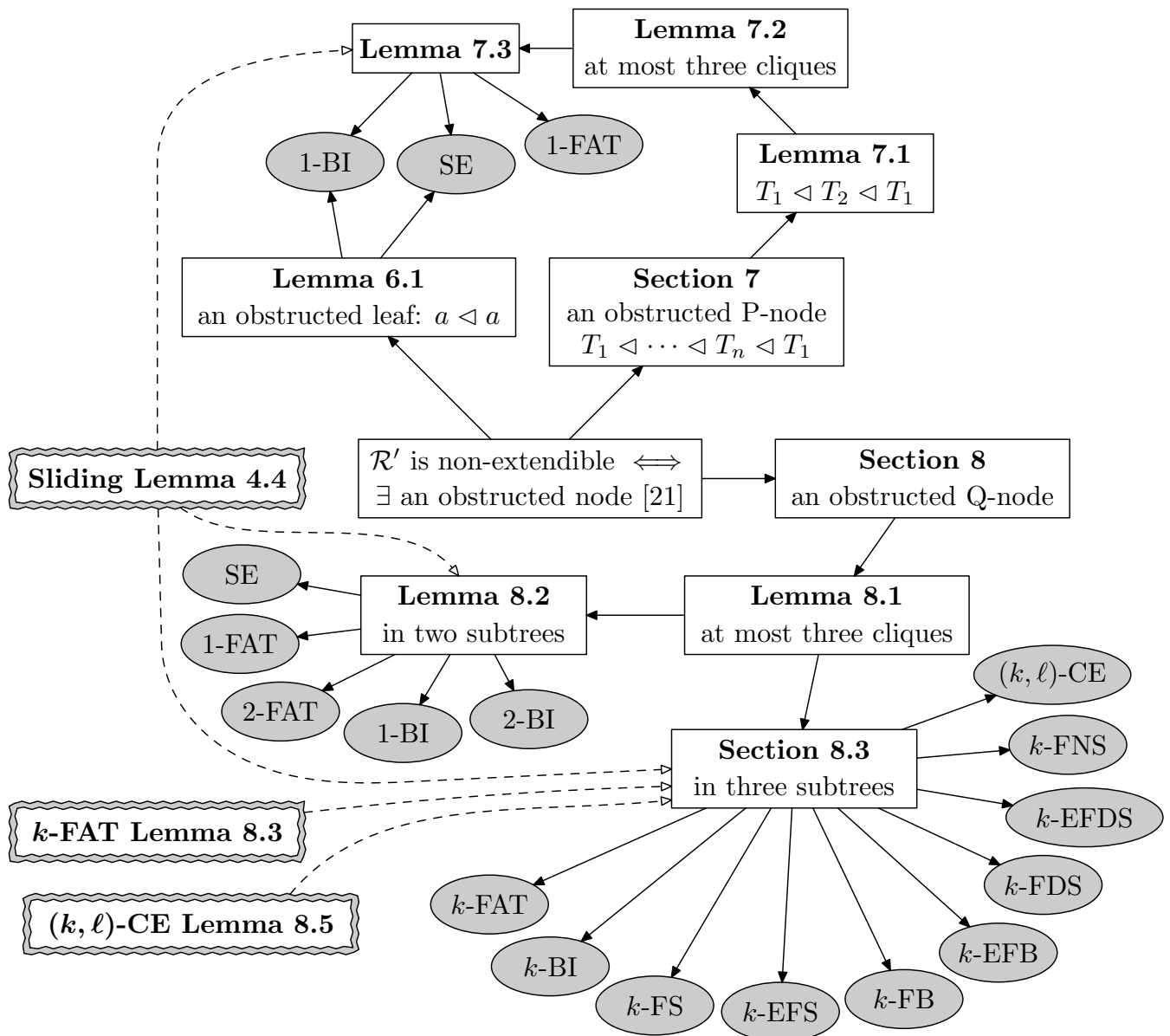


Fig. 15. Overview of the main steps of the proof, it starts in the middle. The obtained obstructions are highlighted in gray, and three tools are depicted with highlighted borders. The most involved case is in Section 8.3.

obstructed leaf (Section 6), an obstructed P -node (Section 7), and an obstructed Q -node (Section 8). Figure 15 shows an overview of the proof.

First, we argue that there exist at most three maximal cliques creating an obstruction. Then, we consider their positions in the MPQ-tree and their open intervals from the definition of \triangleleft . We use tools of Sections 3 and 4 to derive positions of several pre-drawn intervals forming one of the obstructions.

In Section 8.2, we prove a key tool called k -FAT Lemma 8.3: If three non-adjacent vertices x_k , y_k , and z_k are pre-drawn in an order that is different from their order in the sections of a Q -node, then they induce a k -FAT obstruction. The proof is done by induction for k , and it explains why complicated obstructions are needed.

6 Obstructed Leaves

Suppose that some clique-point a cannot be placed, so $\downarrow_a = \emptyset$. In terms of \triangleleft , we get $a \triangleleft a$. Since \triangleleft is a strict partial ordering, this already makes the partial representation non-extendible.

Lemma 6.1 (The leaf case). *If a leaf is obstructed, then G and \mathcal{R}' contain an SE , or 1-BI obstruction.*

Proof. We name the vertices as in the definition of the 1-BI obstructions. Suppose that the leaf corresponds to a maximal clique a such that $\downarrow_a = \emptyset$.

Let $u \in P^{\leftarrow}(a)$ and $v \in P^{\rightarrow}(a)$ (possibly $u = v$). Since I_a is a subinterval of $\bigcap_{w \in P(a)} \langle w \rangle'$ and $\downarrow_a = \emptyset$, every point of $[\ell(v), r(u)]$ is covered by some pre-drawn interval not contained in $P(a)$. Let $\langle x_1 \rangle'$ be one such interval covering $\ell(v)$ and let $\langle z_1 \rangle'$ be one such interval covering $r(u)$ (again, possibly $x_1 = z_1$); see Fig. 16. Let P_1 be a shortest path from x_1 to z_1 consisting of pre-drawn intervals not in $P(a)$.

We prove that the relative pre-drawn position of u , v , x_1 , and z_1 makes the partial representation non-extendible. The maximal clique a does not contain

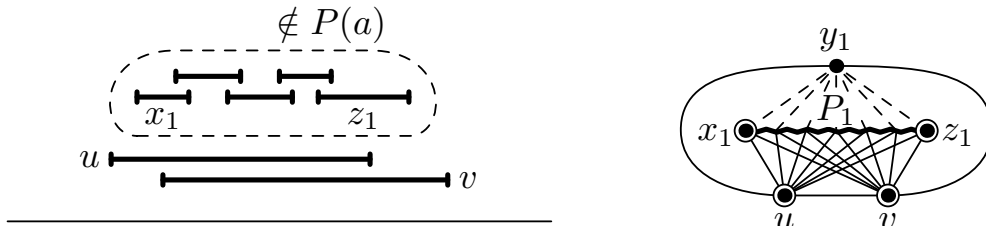


Fig. 16. A construction leading to a 1-BI obstruction.

any vertex of P_1 . Since the vertices of P_1 induce a connected subgraph, by Lemma 3.5 there exists $y_1 \in a$ which is non-adjacent to all vertices of P_1 . Hence, these (at most) five vertices together with P_1 create either a 1-BI obstruction (when $\ell(u) < r(v)$), or an SE obstruction (when $\ell(u) = r(v)$, for which $x = x_1 = z_1$ and we can free it). We note that this obstruction might not be minimal, in which case we can remove some vertices and get one of the minimal obstructions illustrated in Fig. 4 and 7. \square

7 Obstructed P-nodes

If a P-node is obstructed, then it has some subtrees T_1, \dots, T_n forming the cycle $T_1 \triangleleft T_2 \triangleleft \dots \triangleleft T_n \triangleleft T_1$. We start by showing that the specific structure of \triangleleft forces the existence of a two-cycle, so we can assume that $n = 2$.

Lemma 7.1. *If a P-node is obstructed, then it has two subtrees T_1 and T_2 such that $T_1 \triangleleft T_2 \triangleleft T_1$.*

Proof. The proof is illustrated in Fig. 17a. Let $T_1 \triangleleft \dots \triangleleft T_n \triangleleft T_1$ be a shortest cycle for the obstructed P-node. To get a contradiction, we assume $n \geq 3$. Since $T_1 \triangleleft T_2$, there exist $a \in T_1$ and $b \in T_2$ such that $a \triangleleft b$. Similarly, there exist $c \in T_2$ and $d \in T_3$ such that $c \triangleleft d$. We know that I_a is on the left of I_b , and I_c is on the left of I_d . We analyze the remaining relative positions.

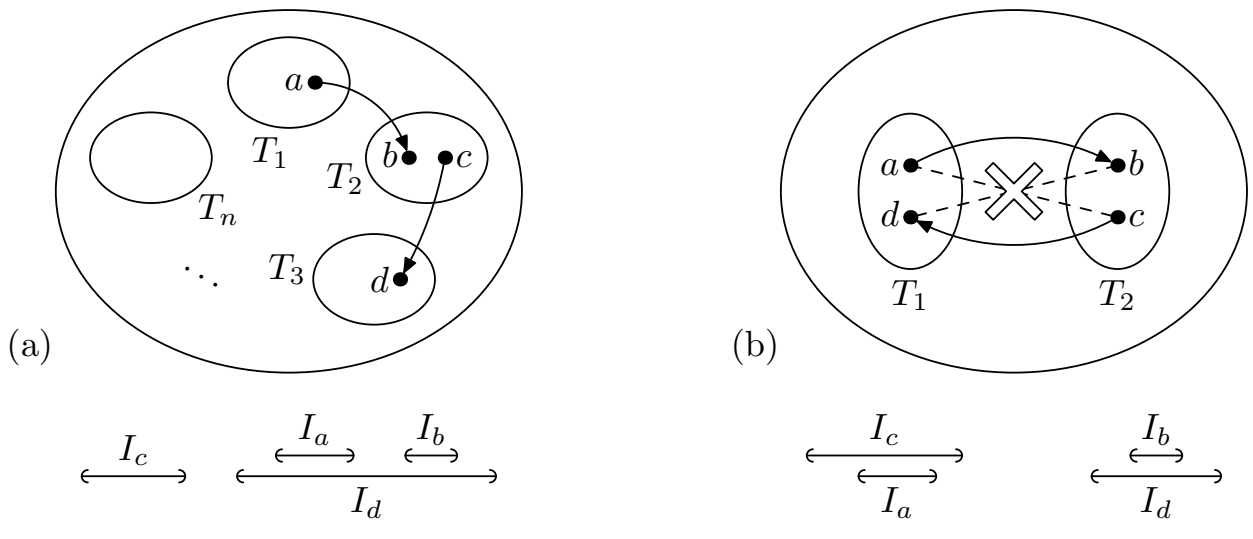


Fig. 17. (a) At the top, a shortest n -cycle of \triangleleft on the children of a P-node. At the bottom, the derived positions of the open intervals. (b) At the top, the four cliques involved in a two-cycle in \triangleleft . The cliques a and c are incomparable, and so are b and d . At the bottom, one of the four possible configurations of the open intervals.

First, I_d is not on the right of I_a , since otherwise $T_1 \triangleleft T_3$ and a shorter cycle would exist. Additionally, I_d is not on the left of I_b , since we would get $T_3 \triangleleft T_2$, and T_2 and T_3 would form a two-cycle. According to Lemma 4.2, no single overlaps of open intervals are allowed, so I_d necessarily contains both I_a and I_b ; see Fig. 17a. Therefore, I_c is on the left of I_a , so $T_2 \triangleleft T_1$ and we get a two-cycle. \square

To create a two-cycle, at most four cliques are enough. Aside from Lemma 4.2, so far we have not used that \triangleleft arises from a partial interval representation. Next, we use properties of the MPQ-tree.

Lemma 7.2. *A two-cycle $T_1 \triangleleft T_2 \triangleleft T_1$ is created by at most three cliques.*

Proof. The proof is depicted in Fig. 17b. Suppose that this two-cycle is given by four cliques $a, d \in T_1$ and $b, c \in T_2$ such that $a \triangleleft b$ and $c \triangleleft d$. Assume for contradiction that no three of these cliques define the two-cycle, i.e., a and c are incomparable, and so are b and d . According to Lemma 4.2, $I_a \subseteq I_c$ or $I_a \supseteq I_c$, and analogously for I_b and I_d . In all of the four cases, I_c is on the left of I_b , and I_d is on the right of I_a .

We look at the case where $I_a \subseteq I_c$ and $I_b \subseteq I_d$, as in Fig. 17b. By Lemma 4.3, we have $P(c) \subseteq P(a)$. Therefore, $P(c)$ contains no vertices from the sections of T_2 . Similarly, $P(d) \subseteq P(b)$, and $P(d)$ contains no vertices from the sections of T_1 . Therefore $P(c) = P(d)$, which implies $I_c = I_d$, a contradiction. The other cases can be analyzed similarly. \square

It remains to put these results together and characterize the possible obstructions.

Lemma 7.3 (The P-node case). *If a P-node is obstructed, then G and \mathcal{R}' contain an SE, 1-FAT, or 1-BI obstruction.*

Proof. According to Lemma 7.1, the obstructed P-node has a two-cycle in \triangleleft . By Lemma 7.2, there are at most three maximal cliques defining this cycle. First assume that this cycle is defined by two cliques $a \in T_1, b \in T_2$ such that $a \triangleleft b \triangleleft a$. According to the definition of \triangleleft , this implies that $I_a = I_b$, both of length zero. Therefore $P(a) = P(b)$. Let $u \in P^{\leftarrow}(a)$ and $v \in P^{\rightarrow}(a)$ (possibly $u = v$); we have that $\langle u \rangle' \cap \langle v \rangle'$ is a singleton. Since a and b are two maximal cliques, there exists $x \in a \setminus b$ and $y \in b \setminus a$. We get an SE obstruction.

It remains to deal with the case where three cliques define the two-cycle. Let $a, c \in T_1$ and $b \in T_2$ such that $a \triangleleft b \triangleleft c$. We have three non-intersecting

intervals whose left-to-right order is I_a , I_b and I_c . Since I_a and I_c are disjoint, one of the sets $P(a) \setminus P(c)$ and $P(c) \setminus P(a)$ is non-empty. Without loss of generality, we assume that $P(a) \setminus P(c) \neq \emptyset$. Let $p \in P(a) \setminus P(c)$; then p belongs to sections of T_1 , and as a consequence $p \notin P(b)$. Therefore $\langle p \rangle'$ is on the left of I_b . We distinguish two cases.

Case 1: $P(b) \setminus P(c) \neq \emptyset$. We choose $q \in P(b) \setminus P(c)$. Then q belongs to sections of T_2 , and $\langle q \rangle'$ is between $\langle p \rangle'$ and I_c . In the next paragraph we show that there also exists $r \in P(c) \setminus P(b)$. Then r belongs to sections of T_1 , and $\langle r \rangle'$ is on the right of $\langle q \rangle'$, as in Fig. 18a. By Lemma 3.3(ii), $G[T_1]$ is connected; let P_1 be a shortest path from p to r in $G[T_1]$. We obtain a 1-FAT obstruction for $x_1 = p$, $y_1 = q$ and $z_1 = r$.

It remains to show that such r exists. Suppose for contradiction that $P(c) \setminus P(b) = \emptyset$. Since $P(c) \subsetneq P(b)$, no vertex of $P(c)$ appears in sections of T_1 , and we get $P(c) \subsetneq P(a)$. Consequently, every pre-drawn interval of $P(c)$ contains $[\curvearrowright(a), \curvearrowright(c)]$. The position of I_c implies that every point of $[\curvearrowright(a), \curvearrowright(c)]$ is covered by some pre-drawn interval not contained in $P(c)$. In particular, there exists a path from p to q consisting of such intervals. Since p belongs to sections of T_1 and q belongs to sections of T_2 , every path from p to q contains a vertex of the section of the P-node, or of a section above it; hence, the path contains a vertex belonging to c . We obtain a contradiction.

Case 2: $P(b) \setminus P(c) = \emptyset$. Then there exists $r \in P(c) \setminus P(b)$. We again observe that $\langle r \rangle'$ is on the right of I_b , as depicted in Fig. 18b. Furthermore, $P(b) \subseteq P(a) \cap P(c)$, so every pre-drawn interval of $P(b)$ contains $[\curvearrowright(a), \curvearrowright(c)]$.

We construct a 1-BI obstruction and we name the vertices as in the definition. Let $u \in P^{\leftarrow}(b)$ and $v \in P^{\rightarrow}(b)$ (possibly $u = v$). Since p does not

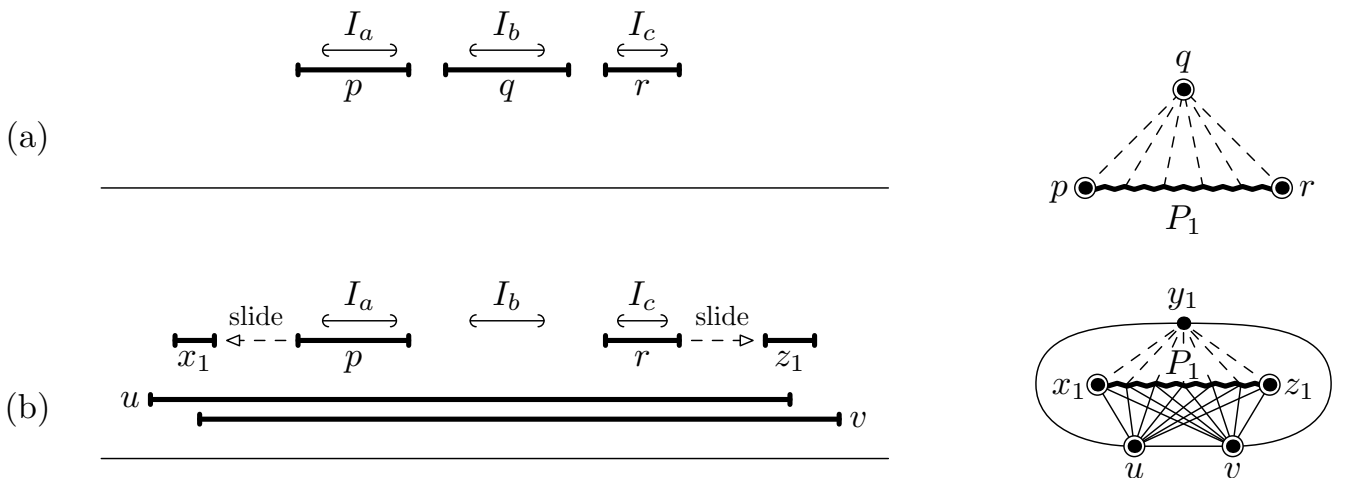


Fig. 18. The two cases of the proof of Lemma 7.3. (a) Case 1 leads to a 1-FAT obstruction. (b) Case 2 leads to a 1-BI obstruction.

necessarily cover $\ell(v)$ and r does not necessarily cover $r(u)$, we might not be able to construct a 1-BI obstruction with $x_1 = p$ and $z_1 = q$. We instead use Sliding Lemma 4.4. By applying it (flipped) to I_b, I_a and p , we obtain a pre-drawn interval x_1 covering $\ell(v)$ (possibly $x_1 = p$). By applying it to I_b, I_c and r , we obtain a pre-drawn interval z_1 covering $r(u)$ (possibly $z_1 = r$). Furthermore, x_1 and z_1 belong to sections of T_1 . Since $G[T_1]$ is connected by Lemma 3.3(ii), there exists a shortest path P_1 from x_1 to z_1 containing no vertex of b . By Lemma 3.5, there exists $y_1 \in b$ non-adjacent to all vertices of P_1 . We obtain a 1-BI obstruction. \square

8 Obstructed Q-nodes

Suppose that a Q-node with subtrees T_1, \dots, T_n is obstructed. Then the two possible orderings of this Q-node are not compatible with \triangleleft . Notice that at most four cliques are sufficient to create the obstruction. We next prove that at most three cliques are already sufficient.

Lemma 8.1. *If a Q-node is obstructed, there exists an obstruction created by at most three maximal cliques.*

Proof. Suppose that an obstruction is created by four cliques $a \in T_\alpha, b \in T_\beta, c \in T_\gamma$ and $d \in T_\delta$ such that $\alpha < \beta, \gamma < \delta, a \triangleleft b$, and $c \triangleright d$. We know that I_a is on the left of I_b , and I_c is on the right of I_d . Notice that the four subtrees $T_\alpha, T_\beta, T_\gamma$ and T_δ are not necessarily distinct. We classify all possible orderings $<$ of $\alpha, \beta, \gamma, \delta$ in two general cases, namely, $\alpha \neq \gamma$ and $\alpha = \gamma$. In the first case, we may assume without loss of generality that $\alpha < \gamma$.

Case 1: $\alpha < \gamma < \delta$ (see Fig. 19a). Consider the relative positions of I_c and I_d with respect to I_a . If I_d is to the left of I_a , we have $d \triangleleft a \triangleleft b$, and these

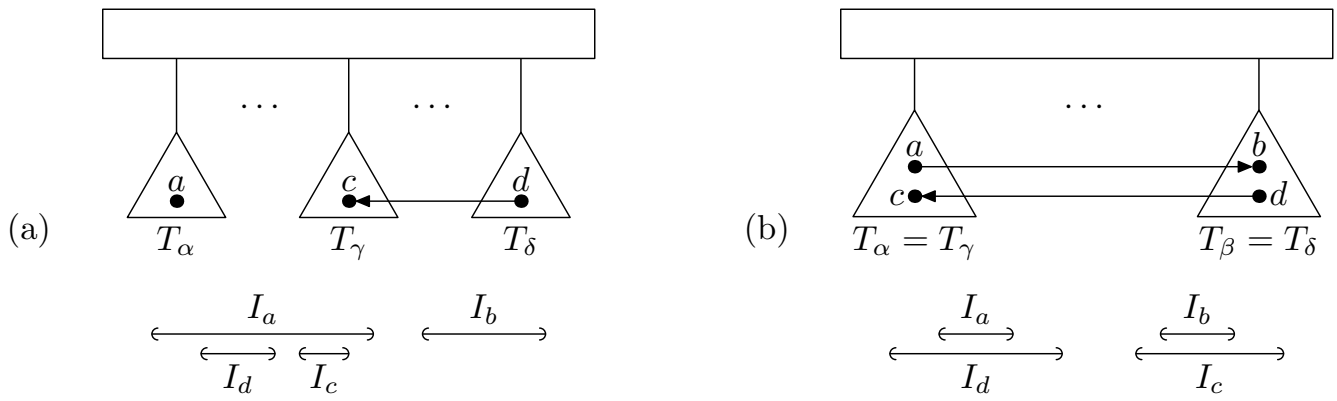


Fig. 19. Two cases of the proof of Lemma 8.1. The Q-node is depicted in the top, while in the bottom we have the relative positions of the intervals.

three cliques already create an obstruction. If I_c is to the right of I_a , then we get $a \triangleleft c$ and $c \triangleright d$, creating an obstruction. If neither happens, then I_c and I_d are subintervals of I_a . Thus $c, d \triangleleft b$. If $\beta \leq \gamma$, we have $a \triangleleft b$ and $b \triangleright d$, creating an obstruction. If $\beta > \gamma$, then $d \triangleleft c \triangleleft b$, which also creates an obstruction.

Case 2: $\alpha = \gamma$ (see Fig. 19b). If I_c does not intersect I_b , or I_d does not intersect I_a , it is easy to see that three of the cliques already create an obstruction. Suppose next that these intersections occur. Then $d \triangleleft b$. If $\delta < \beta$ or $\beta < \delta$, it is again easy to show that three cliques are enough to create an obstruction. It only remains to consider the case where $\alpha = \gamma < \beta = \delta$.

Since the intervals I_c and I_a are non-intersecting, we may assume without loss of generality that there exists $x \in P(a) \setminus P(c)$. This vertex x belongs to sections of T_α . Thus $x \notin P(d)$, and we get that $I_a \subsetneq I_d$. By Lemma 4.3, $P(d) \subsetneq P(a)$; in particular, $P(d)$ contains no private pre-drawn interval from sections of T_β , and all pre-drawn intervals of $s_\beta(Q)$ are also contained in $s_\alpha(Q)$.

Since $P(d) \setminus P(b) = \emptyset$, there exists $y \in P(b) \setminus P(d)$ which is contained in sections of T_β . We next apply the argument in the previous paragraph, and obtain $y \notin P(c)$, $I_b \subsetneq I_c$, and $P(c) \subsetneq P(b)$. Consequently, $P(c)$ contains no private pre-drawn intervals from sections of T_α , and all pre-drawn intervals of $s_\alpha(Q)$ are contained in $s_\beta(Q)$. We conclude that $P(c) = P(d)$ and $I_c = I_d$, which gives a contradiction. \square

In summary, we can assume that a minimal obstruction involves at most three maximal cliques. These three cliques belong to either two or three different subtrees.

In the rest of the section, many figures describe positions of derived pre-drawn intervals in sections of the Q-node and its subtrees; for instance Fig. 20. Some of these intervals necessarily belong to sections of the Q-node, since they belong to maximal cliques of several subtrees; for instance t_2 in Fig. 20. But for the remaining intervals, it is not important to distinguish whether they belong to sections of the Q-node or one of its subtrees, only their relative positions in the Q-node matter; for instance q and x_1 in Fig. 20.

8.1 Cliques in Two Different Subtrees

In this section, we deal with the case where the maximal cliques belong to two different subtrees.

Lemma 8.2 (The Q-node case, Two Subtrees). *If at most three cliques creating the obstruction belong to two different subtrees, then G and \mathcal{R}' contain an SE, 1-FAT, 2-FAT, 1-BI, or 2-BI obstruction.*

Proof. The proof is similar to that of Lemma 7.3. If two maximal cliques create an obstruction, we can argue as in the first paragraph of the proof of Lemma 7.3, and we obtain an SE obstruction. It remains to deal with the case of three maximal cliques a , b , and c .

We can assume that $a \triangleleft b \triangleleft c$ and that, for some $i < j$, we have $a, c \in T_i$ and $b \in T_j$. Furthermore, without loss of generality, there exist $p \in P(a) \setminus P(c)$. Since p belongs to sections of T_i , then $p \notin P(b)$, and thus $\langle p \rangle'$ lies to the left of I_b . We distinguish two cases.

Case 1: $P(b) \setminus P(c) \neq \emptyset$. Then there exists $q \in P(b) \setminus P(c)$ such that $\langle q \rangle'$ lies between $\langle p \rangle'$ and I_c . Since q is non-adjacent to p , it belongs to sections of either Q or T_j . Notice that in any case $s_q^{\leftarrow}(Q)$ is on the right of $s_i(Q)$. Arguing as in Case 1 of the proof of Lemma 7.3, we observe that there exists $r \in P(c) \setminus P(b)$. Furthermore, it follows that $\langle r \rangle'$ lies to the right of $\langle q \rangle'$; see Fig. 20a on the left.

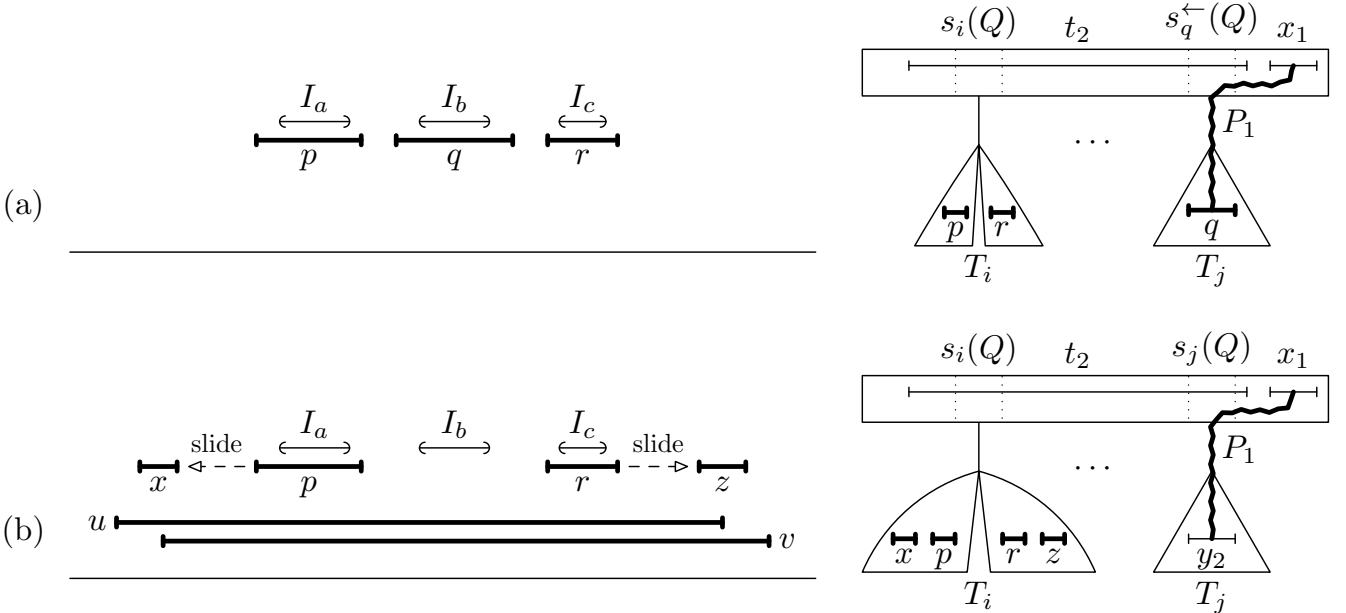


Fig. 20. (a) Case 1: The pre-drawn intervals and the situation in the MPQ-tree for $s_i(Q) \subsetneq s_q^{\leftarrow}(Q)$. (b) Case 2: The pre-drawn intervals and the situation when there exists no path from x to z avoiding the vertices of b .

If there exists a path P_1 from p to r avoiding $N[q]$, we get a 1-FAT obstruction for $x_1 = p$, $y_1 = q$, $z_1 = r$ and P_1 . By Lemma 3.2, we know that $s_i(Q) \neq s_q^{\leftarrow}(Q)$. If $s_i(Q) \not\subseteq s_q^{\leftarrow}(Q)$, then there exists some $w \in s_i(Q) \setminus s_q^{\leftarrow}(Q)$. Therefore, $P_1 = pwr$ is such a path. It remains to deal with the case where no such path P_1 exists, which implies that $s_i(Q) \subsetneq s_q^{\leftarrow}(Q)$; see Fig. 20a on the right.

Consider the set $W = s_i(Q)$. Let t_2 be a vertex of W whose section $s_{t_2}^{\rightarrow}(Q)$ is leftmost. Let C be the component of $G[Q] \setminus W$ containing q . Since $s_q^{\leftarrow}(Q) \setminus W$ is non-empty, C consists of the vertices of at least two subtrees of the Q -node. If t_2 was adjacent to all vertices of C , it would be possible to flip the ordering of this component, contradicting the fact that there are only two possible orderings for Q . Therefore, t_2 is not adjacent to all vertices of C . We choose $x_1 \in C \setminus N[t_2]$ whose section $s_{x_1}^{\leftarrow}(Q)$ is leftmost. Let P_1 be a shortest path from q to x_1 whose inner vertices are adjacent to t_2 . It follows that $x_2 = p$, $y_2 = q$, $z_2 = r$, $P_2 = x_2t_2$, t_2 , x_1 , and P_1 define a 2-FAT obstruction. (By Lemma 3.4, all inner vertices of P_1 are adjacent to t_2 .) \square

Case 2: $P(b) \setminus P(c) = \emptyset$. Then there exists $r \in P(c) \setminus P(b)$. Since $\langle r \rangle'$ lies on the right of I_b , the vertex r is not contained in a and it belongs to sections of T_i . We use the same approach as in Case 2 of the proof of Lemma 7.3. Since $P(b) \subseteq P(a) \cap P(c)$, every pre-drawn interval of $P(b)$ covers $[\curvearrowright(a), \curvearrowright(c)]$. Let $u \in P^{\leftarrow}(b)$ and $v \in P^{\rightarrow}(b)$ (possibly $u = v$).

By applying Sliding Lemma 4.4 twice, we get $x, z \notin P(b)$ such that $\langle x \rangle'$ covers $\ell(v)$ and $\langle z \rangle'$ covers $r(u)$; see Fig. 20b on the left. Suppose that there exists a path $P_{x,z}$ from x to z avoiding all vertices of b . Let $x_1 = x$, $z_1 = z$, and P_1 be a shortest path from x_1 to z_1 in $G[Q] \setminus b$. By Lemma 3.5, there exists $y_1 \in b$ non-adjacent to P_1 . We obtain a 1-BI obstruction.

Suppose next that there is no path $P_{x,z}$ avoiding b . We know that x and y belong to sections of T_i , since there exist paths $P_{x,p}$ and $P_{r,z}$ avoiding b , from the above applications of Sliding Lemma 4.4. Since no path $P_{x,z}$ avoiding b exists, we have $s_i(Q) \subsetneq s_j(Q)$. As in Case 1, let $W = s_i(Q)$, and let t_2 be a vertex of W whose section $s_{t_2}^{\rightarrow}(Q)$ is leftmost (possibly $t_2 = u$ or $t_2 = v$). We again infer that t_2 is not adjacent to all vertices of C , where C is the component of $G[Q] \setminus W$ containing $b \setminus W$. We choose $x_1 \in C \setminus N[t_2]$ whose section $s_{x_1}^{\leftarrow}(Q)$ is leftmost. Since $s_i(Q) \subsetneq s_j(Q) \subseteq b$, there exists $y_2 \in b$ non-adjacent to x and z . We get a 2-BI obstruction for $x_2 = x$, y_2 , $z_2 = z$, u , v , a shortest path P_1 from y_2 to x_1 in C , and $P_2 = x_2t_2$. (By Lemma 3.4, all inner vertices of P_1 are adjacent to t_2 .) \square

8.2 k -FAT and (k, ℓ) -CE Lemmas

In this section, we give two tools for the case, analyzed in Section 8.3, where the three maximal cliques creating the obstruction belong to three different subtrees. These tools give insight into the structure of the Q-nodes, and explain the way in which complex obstructions such as k -FAT and (k, ℓ) -CE obstructions are formed.

k -FAT Lemma. First, we present a useful lemma that allows to locate k -FAT obstructions. The key idea of the proof is similar to Case 1 of the proof of Lemma 8.2, but applied inductively for k .

Lemma 8.3 (k -FAT). *Let Q be a Q-node with children T_1, \dots, T_n , and let a, b and c be three cliques of $T[Q]$ contained respectively in T_α, T_β and T_γ , for $\alpha < \beta < \gamma$. Let $x_k \in P(a), y_k \in P(c)$ and $z_k \in P(b)$ be three disjoint pre-drawn intervals such that $\langle y_k \rangle'$ is between $\langle x_k \rangle'$ and $\langle z_k \rangle'$. Then $G[Q]$ and $\mathcal{R}'[\{x_k, y_k, z_k\}]$ contain a k -FAT obstruction.*

Proof. The proof, illustrated in Fig. 21, is by induction. We always denote the vertices as in the definition of k -FAT obstructions. If we find a 1-FAT or 2-FAT obstruction, the statement is true. Otherwise, we recurse on a smaller part of the Q-node, where we find a structure identical to a $(k - 1)$ -FAT obstruction, except for the fact that the vertex x_{k-1} is free. Together with some vertices in the remainder of the Q-node, we obtain a k -FAT obstruction. We next provide the details.

Let k be some yet unspecified integer, determined by the recursion. We want to argue that $G[Q]$ contains a k -FAT obstruction because the ordering of $\langle x_k \rangle', \langle y_k \rangle'$ and $\langle z_k \rangle'$ is incorrect (in every representation, $\langle z_k \rangle'$ is between $\langle x_k \rangle'$ and $\langle y_k \rangle'$). Suppose that there exists a path from x_k to z_k whose inner vertices are non-adjacent to y_k . Then we obtain a 1-FAT obstruction. It remains to deal with the harder situation where no such path exists.

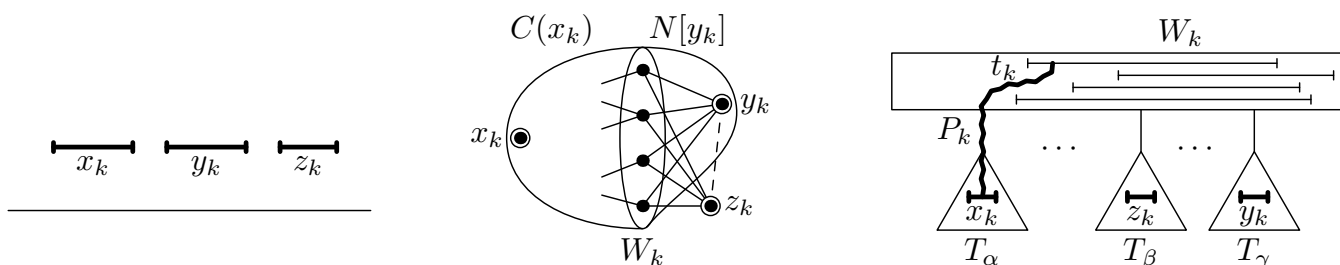


Fig. 21. On the left, the position of the pre-drawn intervals. In the middle, the construction of $W_k \subsetneq N[y_k]$ in $G[Q]$. On the right, the Q-node with the three subtrees and the intervals of W_k depicted in its sections.

Let $C(x_k)$ be the connected component of $G[Q] \setminus N[y_k]$ containing x_k . By our assumption, $z_k \notin C(x_k)$. We denote by W_k the subset of $N[y_k]$ containing those vertices that are adjacent to some vertex of $C(x_k)$; see Fig. 21, middle. Notice that the vertices of $C(x_k)$ appear only in sections and subtrees to the left of $s_\beta(Q)$. Therefore, every vertex of W_k lies in the sections of Q and stretches from the left of $s_\beta(Q)$ to $s_\gamma(Q)$; see Fig. 21, right. In other words, $W_k \subseteq s_\beta(Q) \cap s_\gamma(Q)$ and every vertex of W_k is adjacent to z_k .

Let C be a connected component of $G[Q] \setminus W_k$. If C contains a vertex from some section of Q , we call it *big*. Notice that in this situation C has a vertex contained in two consecutive sections of Q and their subtrees. Otherwise, C consists of some vertices of a subtree of Q , and we call it *small*. The section above a subtree containing a small component is a subset of W_k . Additionally, if two small components are placed in two different subtrees, the two sections above these subtrees are different.

The graph $G[Q] \setminus W_k$ is disconnected, as x_k and z_k belong to different components. Let us denote the connected component containing y_k by $C(y_k)$, and the one containing z_k by $C(z_k)$. Let t_k be a vertex of W_k whose section $s_{t_k}^\rightarrow(Q)$ is leftmost. Let P_k be a shortest path from x_k to t_k in $G[C(x_k) \cup \{t_k\}]$; see Fig. 21, right. We distinguish two cases.

Case 1: $C(y_k) \neq C(z_k)$. This case is very similar to the proof of Lemma 8.2; see Fig. 22a. Every vertex of W_k is adjacent to some vertex of $C(x_k)$ and to some vertex of $C(y_k)$. Therefore, it is also adjacent to every vertex of $C(z_k)$. If $C(z_k)$ was big, then we could reverse its sections in the Q -node, contradicting the fact that there are only two possible orderings for a Q -node. Therefore, $C(z_k)$ is small. Notice that then $C(y_k)$ is not small, since otherwise we would get $s_\beta(Q) = W_k = s_\gamma(Q)$, contradicting Lemma 3.2. Thus, $C(y_k)$ is big.

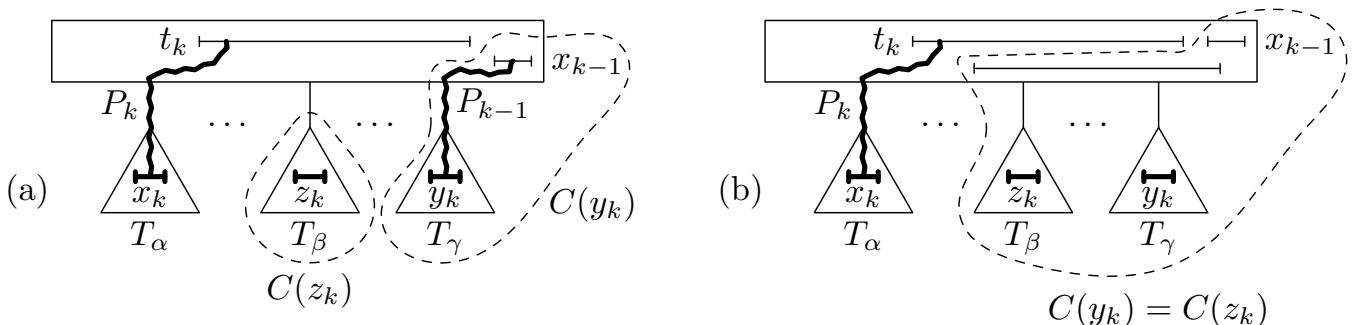


Fig. 22. (a) In Case 1, there exists a path P_{k-1} from x_{k-1} to y_k whose inner vertices avoid z_k . (b) In Case 2, we have $C(y_k) = C(z_k)$ and such a path might no longer exist. For instance, every path from x_{k-1} to y_k in $C(y_k)$ might use the depicted interval in the sections of Q , which is also adjacent to z_k .

Let us set $y_{k-1} = z_k$ and $z_{k-1} = y_k$. The vertex t_k is not universal for $C(y_k)$; otherwise, every vertex of W_k would be universal and this would give additional orderings of $C(y_k)$ in Q . Let x_{k-1} be a vertex of $C(y_k) \setminus N[t_k]$ whose section $s_{x_{k-1}}^{\leftarrow}(Q)$ is leftmost. Notice that $s_{x_{k-1}}^{\leftarrow}(Q)$ is always the next section to $s_{t_k}^{\rightarrow}(Q)$. Let P_{k-1} be a shortest path from x_{k-1} to z_{k-1} in $C(y_k)$. By Lemma 3.4, all inner vertices of P_{k-1} are adjacent to t_k . Since this path lies in $C(y_k)$, the inner vertices are non-adjacent to y_{k-1} , x_k and P_k . We have constructed a 2-FAT obstruction.

Case 2: $C(y_k) = C(z_k)$. In this case, the component $C(y_k)$ is big; see Fig. 22b. Therefore, similarly as above, t_k is not universal for $C(y_k)$. We put $y_{k-1} = z_k$ and $z_{k-1} = y_k$. We choose $x_{k-1} \in C(y_k) \setminus N[t_k]$ in the same way as in Case 1. Notice that x_{k-1} is a non-neighbor of y_{k-1} , since otherwise it would be a neighbor of t_k . On the other hand, x_{k-1} might be adjacent to z_{k-1} or not. If it is, we get a 2-FAT obstruction for $k = 2$ with $P_1 = x_{k-1}z_{k-1}$. If it is not, we proceed as follows.

As before, every shortest path from x_{k-1} to z_{k-1} has all inner vertices adjacent to t_k . Since all vertices of $C(y_k)$ are non-adjacent to x_k and the inner vertices of P_k , every shortest path satisfies this as well. There exists a shortest path from x_{k-1} to z_{k-1} in $C(y_k)$, but we cannot guarantee that the inner vertices of this path are non-adjacent to y_{k-1} . We solve this issue by applying the entire argument of the proof recursively to $C(y_k)$.

In every representation extending the partial representation, the intervals of $C(x_k)$ form a connected subset of the real line placed to the left of $\langle y_k \rangle'$. Therefore, $\langle t_k \rangle$ stretches from $C(x_k)$ to $\langle z_k \rangle'$, covering $\langle y_k \rangle'$. Thus $\langle x_{k-1} \rangle$ is placed to the right of $\langle z_k \rangle' = \langle y_{k-1} \rangle'$ in every extending representation (see Fig. 5b). Again, $\langle y_{k-1} \rangle'$ has to be placed between $\langle x_{k-1} \rangle$ and $\langle z_{k-1} \rangle'$. We assume that $\langle x_{k-1} \rangle$ is pre-drawn on the right of $\langle y_{k-1} \rangle'$ and repeat the same argument for $C(y_k)$ and the MPQ-tree restricted to these vertices. The role of x_k , y_k and z_k is played by x_{k-1} , y_{k-1} and z_{k-1} , respectively. (The ordering of the pre-drawn intervals is flipped.)

The paragraphs above show the induction step of our proof (by induction on, say, the number of considered sections of Q). By the induction hypothesis, we find a $(k-1)$ -FAT obstruction. By making x_{k-1} free and adding x_k , t_k and P_k , we get a k -FAT obstruction in the original partial representation. Clearly t_k is adjacent to the entire $(k-1)$ -FAT obstruction with the exception of x_{k-1} , since all further vertices are contained in a section to the left of $s_{x_{k-1}}^{\leftarrow}(Q)$. The reason is that we always use shortest paths which are Q -monotone by

Lemma 3.4. By the same reason, they are non-adjacent to the inner vertices of P_k and to x_k , as required.

To make the argument complete, we should check that all the assumptions used throughout the proof apply recursively, in particular the arguments concerning non-universality of t_{k-1} and reversing big components. This is true because both components $C(y_{k-1})$ and $C(z_{k-1})$ of $C(y_k) \setminus W_{k-1}$ appear to the left of x_{k-1} , so t_k and the other vertices of W_k are universal for them. This property is preserved throughout the recursion, so $C(y_\ell)$ and $C(z_\ell)$ are adjacent to all vertices of $W_k, W_{k-1}, \dots, W_{\ell+1}$. Similarly, the rest of the inductive proof can be formalized. \square

The above proof shows that the structure of a Q-node can be highly complicated, leading to complicated obstructions such as k -FAT. Actually, k -FAT Lemma 8.3 is a very useful tool because it can be also applied in situations where not all x_k, y_k , and z_k are pre-drawn, to build other obstructions. Fig. 23 shows an example.

Lemma 8.4. *Consider a k -FAT obstruction H_k for $k > 2$. If we swap the positions of $\langle x_k \rangle'$ and $\langle y_k \rangle'$, then we obtain a new obstruction which contains a 1-FAT obstruction for $x'_1 = y_k, y'_1 = x_k$, and $z'_1 = z_k$. Further, if $k = 2$ and this does not happen, then x_2 is adjacent to t_2 .*

Proof. For $k \geq 3$, the graph $H_k \setminus N[x_k]$ is connected; in particular, there exists a path $P'_1 = y_k t_{k-1} z_k$ avoiding $N[x_k]$. For $k = 2$, there exists a path $P'_1 = y_2 t_2 z_2$ avoiding $N[x_2]$, unless x_2 is adjacent to t_2 . \square

(k, ℓ) -CE Lemma. Suppose that we have the situation in Fig. 24. We can easily show that there is some (k, ℓ) -CE obstruction by applying k -FAT Lemma 8.3

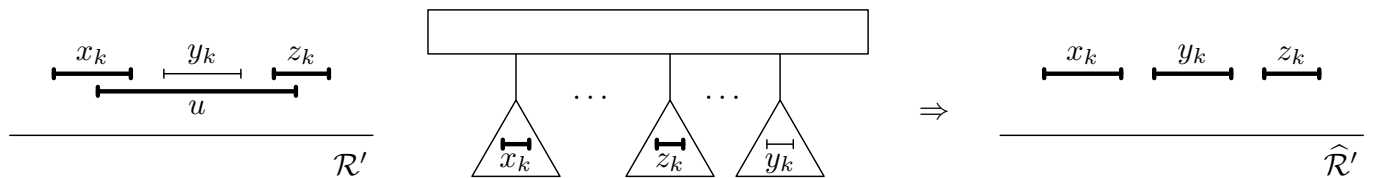


Fig. 23. Suppose that we show that a partial representation \mathcal{R}' has three pre-drawn intervals as on the left, and that there is a vertex y_k adjacent to u and non-adjacent to x_k and z_k . Then $\langle y_k \rangle$ has to be placed between $\langle x_k \rangle'$ and $\langle z_k \rangle'$ in every extending representation. Thus, we can assume it is pre-drawn there and obtain a modified partial representation $\widehat{\mathcal{R}}'$. If we further show that x_k, y_k and z_k are placed in appropriate sections of $G[Q]$ for some Q-node Q , we can apply k -FAT Lemma 8.3 and we get a k -FAT obstruction in $G[Q]$ and $\widehat{\mathcal{R}}'[\{x_k, y_k, z_k\}]$. Together with $\langle u \rangle'$, this forms a k -BI obstruction in G and \mathcal{R}' .

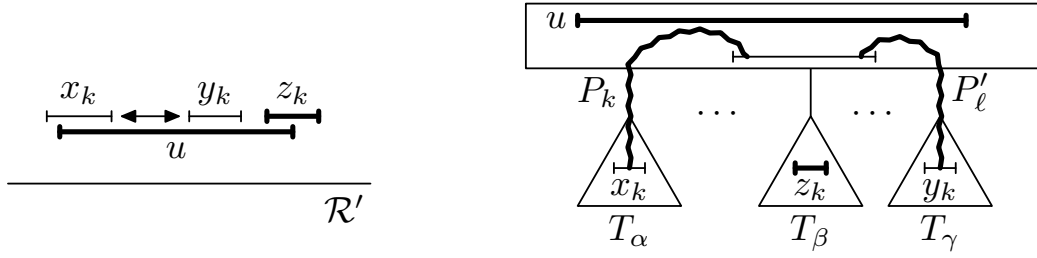


Fig. 24. When $\langle u \rangle'$ single overlaps $\langle z_k \rangle'$, and the vertices x_k , y_k , and z_k are placed in the MPQ-tree as on the right, we get a (k, ℓ) -CE obstruction.

twice, once when $\langle x_k \rangle$ is on the left of $\langle y_k \rangle$ and once when it is on the right. The following lemma reveals its structure in detail.

Lemma 8.5 ((k, ℓ)-CE). *Let Q be a Q -node with children T_1, \dots, T_n , and let a , b and c be three cliques of $T[Q]$ contained respectively in T_α , T_β and T_γ , for $\alpha < \beta < \gamma$. Let $x_k \in a$, $y_k \in c$ and $z_k \in P(b)$ be three non-adjacent vertices having a common pre-drawn neighbor u such that $\langle u \rangle'$ single overlaps $\langle z_k \rangle'$. Then $G[Q] \cup \{u\}$ and $\mathcal{R}'[\{z_k, u\}]$ contain a (k, ℓ) -CE obstruction, where either $\ell = 1$ or $k = \ell = 2$.*

Proof. The simplest case is when there exist a path P_k from x_k to z_k avoiding $N[y_k]$, and a path P'_ℓ from y_k to z_k avoiding $N[x_k]$. Let P_k and P'_ℓ be shortest such paths as in Fig. 24, right. We get a $(1, 1)$ -CE obstruction. By Lemma 3.4, the paths P_k and P'_ℓ are monotone. Therefore, their inner vertices are non-adjacent to each other, with the possible exception of the last vertices before z_k , which can be adjacent or even identical. Concerning minimality, we can always find one of the three finite $(1, 1)$ -CE obstructions depicted in Fig. 8a. The reason is that when paths P_k and P'_ℓ are long, we can take as x_k and y_k one of their inner vertices, making them shorter.

Suppose next that there exists no path P_k from x_k to z_k avoiding $N[y_k]$. Let $C(x_k)$, W_k , and t_k be defined as in the proof of k -FAT Lemma 8.3. Following the argument in that proof, we get the subgraph H_k of a k -FAT obstruction, which is not the complete k -FAT obstruction because x_k and y_k are free.

Case 1: There exists some path P'_ℓ from y_k to z_k avoiding $N[x_k]$. Let P'_ℓ be a shortest such path (notice that $\ell = 1$). Together with the above subgraph H_k , we get a $(k, 1)$ -CE obstruction; see Fig. 25a. In particular, if some vertex $w \in W_k$ is non-adjacent to x_k (possibly $w = t_k$), we can use $P'_\ell = y_k w z_k$.

We note that when $k \geq 3$, such a path P'_ℓ necessarily exists, as we can use $P'_\ell = y_k t_{k-1} z_k$, as argued in Lemma 8.4. Therefore, the $(k, 1)$ -CE obstructions consist of the subgraph H_k together with u ; assuming minimality, we have that either u is adjacent to all vertices of H_k , or $u = t_k$. If $k = 2$, then P'_ℓ might still

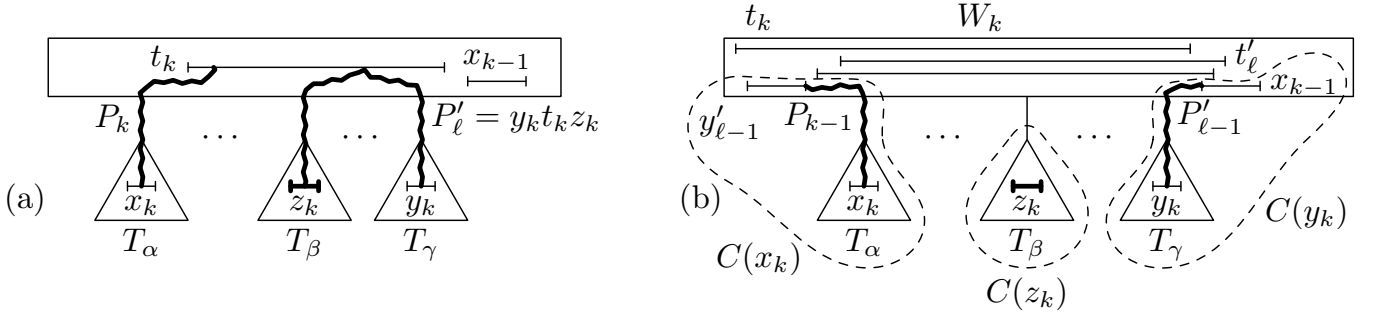


Fig. 25. (a) Case 1: If there exists a path P'_ℓ from y_k to z_k avoiding $N[x_k]$, then we get a $(k, 1)$ -CE obstruction. (b) Case 2: We get a $(2, 2)$ -CE obstruction.

exist but it might be longer and might use inner vertices not contained in H_k . Concerning minimality, we always find one of the three $(2, 1)$ -CE obstructions depicted in Fig. 8b. Indeed, P_2 can be assumed to be of length one or two, since otherwise we could use one of its inner vertices as x_2 . For length two, we get $P'_1 = y_k t_k z_k$. For length one, we get a path P'_1 from z_2 to y_2 , and we can assume that y_2 is adjacent to x_1 (otherwise we could use as y_2 the neighbor of x_1 on P_1).

Case 2: No such path P'_ℓ exists. By Lemma 8.4, $k = 2$. We want to show that there exists a $(2, 2)$ -CE obstruction.

Notice that all vertices $w \in W_k$ are adjacent to x_k , y_k , and z_k , since otherwise there would exist a path $P'_\ell = y_k w z_k$. Hence the vertices of W_k belong to sections of Q , covering all subtrees between T_α and T_γ ; see Fig. 25b. Let $C(y_k)$ and $C(z_k)$ be the components of $G[Q] \setminus W_k$ containing y_k and z_k , respectively. Since there exists no path P'_ℓ , we obtain that $C(x_k)$, $C(y_k)$, and $C(z_k)$ are pairwise different. To determine the structure of a $(2, 2)$ -CE obstruction, we apply the argument from Case 1 of the proof of k -FAT Lemma 8.3 symmetrically twice.

Let t_k be a vertex of W_k having leftmost section $s_{t_k}^\rightarrow(Q)$ and let t'_ℓ be a vertex of W_k having rightmost section $s_{t'_\ell}^\leftarrow(Q)$ (possibly $t_k = t'_\ell$). It is easy to see that $C(z_k)$ is small, otherwise we could flip it and obtain an ordering of the maximal cliques not compatible with the Q-node.

Similarly as in the proof of k -FAT Lemma 8.3, this implies that both $C(x_k)$ and $C(y_k)$ are big. Therefore, t_k is not universal for $C(y_k)$ and t'_ℓ is not universal for $C(x_k)$. As in the proof of k -FAT Lemma 8.3, we choose $x_{k-1} \in C(y_k)$ non-adjacent to t_k and $y'_{\ell-1} \in C(x_k)$ non-adjacent to t'_ℓ . There exist paths P_{k-1} from x_{k-1} to y_k and $P'_{\ell-1}$ from $y'_{\ell-1}$ to x_k . In consequence, we obtain a $(2, 2)$ -CE obstruction.

Regarding minimality, notice that we can assume that y_2 is adjacent to x_1 , and x_2 is adjacent to y'_1 ; otherwise, we could choose as y_2 and x_2 the neighbors of x_1 and y'_1 on the paths P_1 and P'_1 , respectively. We get the four minimal finite (2, 2)-CE obstructions that are illustrated in Fig. 8c. \square

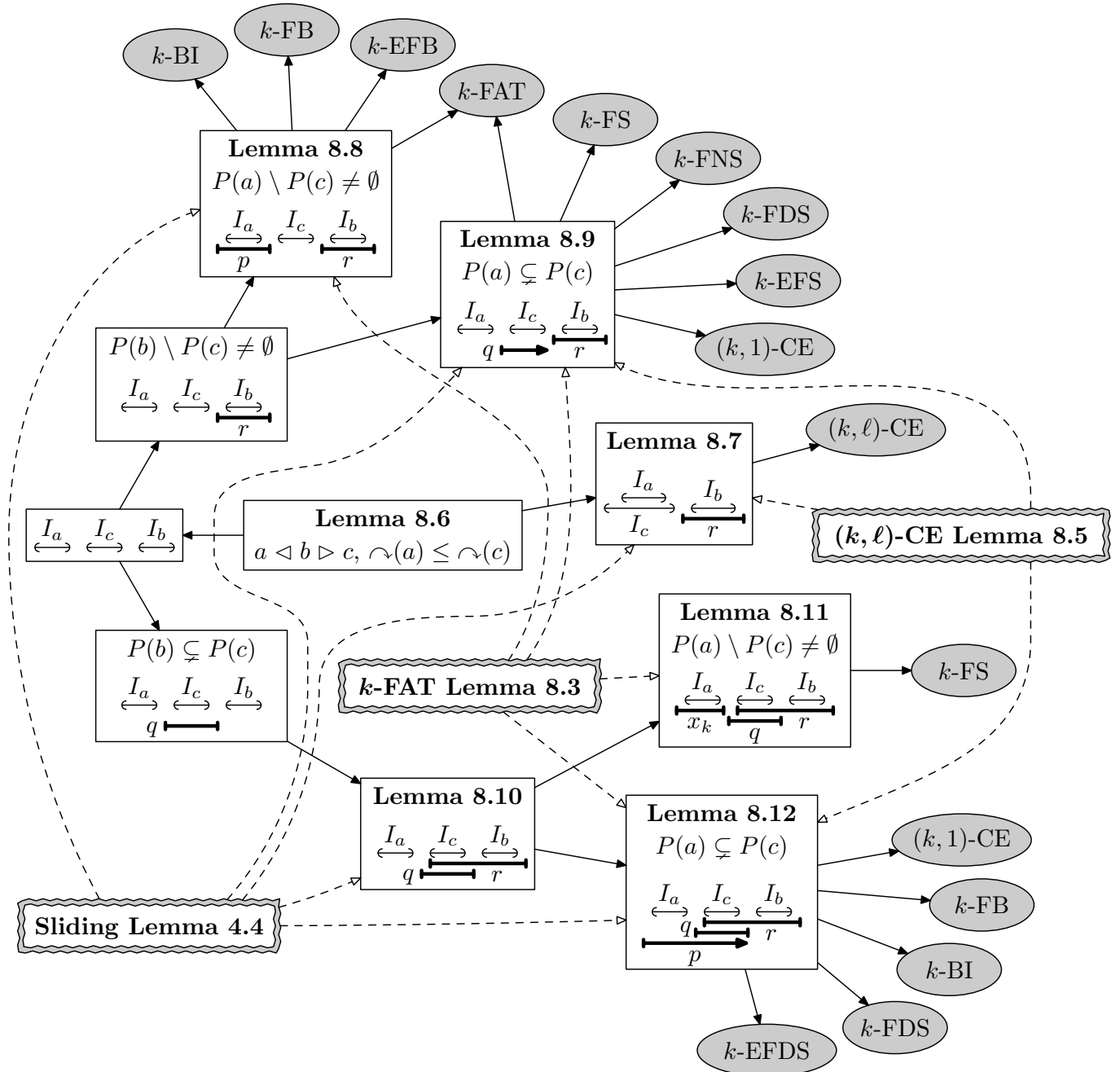


Fig. 26. A summary of Section 8.3. The diagram starts in the middle with Lemma 8.6. Inside the cases, we draw the positions of I_a, I_b, I_c , and some pre-drawn intervals. An arrow at a pre-drawn interval means that it may be further stretched in the given direction. The obtained obstructions are highlighted in gray, the used tools have highlighted borders.

8.3 Cliques in Three Different Subtrees

When a Q-node Q is obstructed by three maximal cliques $a \in T_\alpha$, $b \in T_\beta$ and T_γ , where $\alpha < \beta < \gamma$, the situation is quite complex. Fig. 26 gives an overview of the cases and obstructions obtained in this case.

Lemma 8.6. *Without loss of generality, we can assume that $a \triangleleft b \triangleright c$ and $\curvearrowright(a) \leq \curvearrowright(c)$.*

Proof. Since a, b and c create an obstruction, b is either a minimal or a maximal element in $\triangleleft |_{\{a,b,c\}}$. Without loss of generality (using the flip operation), we can assume that b is maximal, so $a \triangleleft b \triangleright c$. Since we can swap a and c by reversing the Q-node, we can assume that $\curvearrowright(a) \leq \curvearrowright(c)$. \square

Since $a \triangleleft b \triangleright c$, both I_a and I_c appear on the left of I_b . Since $\curvearrowright(a) \leq \curvearrowright(c)$, either I_a contained in I_c , or I_a is on the left of I_c . The first case is easier:

Lemma 8.7. *If I_a is contained in I_c , then G and \mathcal{R}' contain a (k, ℓ) -CE obstruction, where $\ell = 1$ or $2 \geq k \geq \ell$.*

Proof. The proof is illustrated in Fig. 27. By Lemma 4.3, $P(c) \subseteq P(a)$. Since b is placed between a and c in the Q-node Q , every vertex contained in both a and c is contained in b as well. Hence $P(c) \subsetneq P(b)$, and there exists $r \in P(b) \setminus P(c)$. Since $\langle r \rangle'$ is on the right of I_c , it is also on the right of I_a , and thus $r \notin P(a)$.

Let $u \in P^{\leftarrow}(c)$. We apply Sliding Lemma 4.4 to I_c , I_b , and $\langle r \rangle'$. We get a pre-drawn interval $\langle z_k \rangle'$ covering $r(u)$, and an induced path P_{r,z_k} from r to z_k consisting of pre-drawn intervals not in $P(c)$. Therefore z_k is on the left of c in Q . Since all pre-drawn intervals of P_{r,z_k} do not belong to $P(c)$, they are on the right of I_c . Thus they are also on the right of I_a , which implies that they do not belong to $P(a)$. Consequently, z_k is between a and c in Q .

Let $x_k \in a$ and $y_k \in c$ be vertices non-adjacent to z_k . By (k, ℓ) -CE Lemma 8.5, x_k, y_k, z_k , and u create a (k, ℓ) -CE obstruction, for $\ell = 1$ or $2 \geq k \geq \ell$. Notice that the clique associated to z_k is some $b' \neq b$. \square

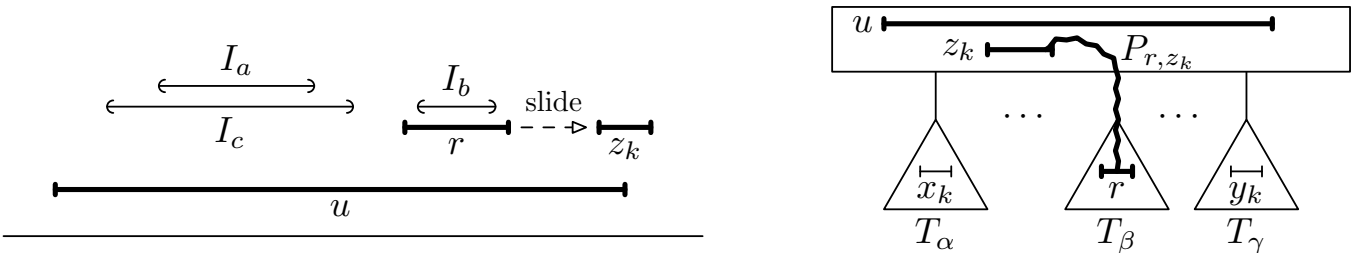


Fig. 27. Proof of Lemma 8.7. On the left, the pre-drawn intervals. On the right, their positions in the MPQ-tree.

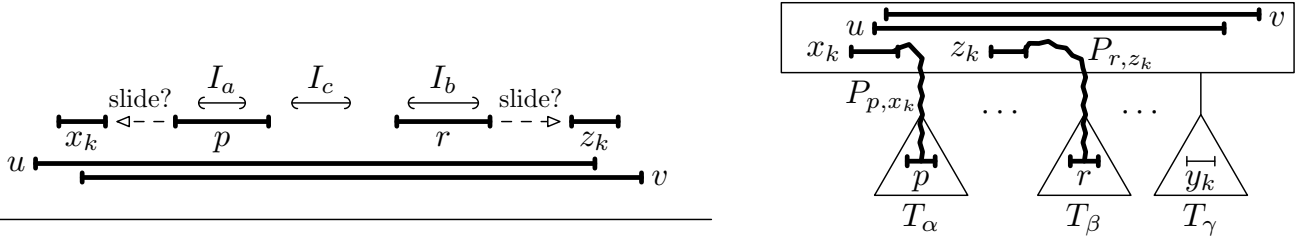


Fig. 28. Proof of Lemma 8.8. On the left, the pre-drawn intervals, with possible sliding on each side. On the right, their positions in the MPQ-tree.

The case where I_a is on the left of I_c is further divided into several subcases. In the next two lemmas, we focus on the situation where $P(b) \setminus P(c) \neq \emptyset$.

Lemma 8.8. *If I_a is on the left of I_c , $P(b) \setminus P(c) \neq \emptyset$ and $P(a) \setminus P(c) \neq \emptyset$, then G and \mathcal{R}' contain a k -FAT, k -BI ($k \leq 2$), k -FB, or k -EFB obstruction.*

Proof. The proof is illustrated in Fig. 28. Let $p \in P(a) \setminus P(c)$ and $r \in P(b) \setminus P(c)$. Then $\langle p \rangle'$ is on the left of I_c , and $\langle r \rangle'$ is on the right of I_c . Clearly, $\langle p \rangle'$ and $\langle r \rangle'$ are disjoint, so p appears in the Q-node on the left of r . Let $u \in P^{\leftarrow}(c)$ and $v \in P^{\rightarrow}(c)$ (possibly $u = v$).

If $r(u) \leq r(r)$, then $z_k = r$. Obviously, z_k is between p and c in the Q-node. Otherwise, $P(c) \subsetneq P(b)$, and we apply Sliding Lemma 4.4 to I_c , I_b , and r . We obtain a pre-drawn interval $\langle z_k \rangle'$ not contained in $P(c)$ covering $r(u)$, and a path P_{r,z_k} whose inner vertices are pre-drawn and not contained in $P(c)$. Notice that all of these pre-drawn vertices are on the right of I_c . Therefore, these vertices are not contained in $P(a)$. In this case, we also get that z_k is between p and c in the Q-node.

Similarly, if $\ell(p) \leq \ell(v)$, then $x_k = p$. Otherwise, we use the flipped version of Sliding Lemma 4.4 to I_c , I_a , and p , which gives a pre-drawn interval $\langle x_k \rangle'$ not contained in $P(c)$ covering $\ell(v)$. By a similar argument, in both cases, we show that x_k is on the left of z_k in the Q-node.

Let $y_k \in c$ be a vertex non-adjacent to z_k (possibly, $y_k = u$ or $y_k = v$). Such a vertex exists because z_k is on the left of c in the Q-node. Notice that y_k is also non-adjacent to x_k . Since y_k is adjacent to u and v , in every extending representation $\langle y_k \rangle$ is between $\langle x_k \rangle'$ and $\langle z_k \rangle'$. So we can assume that it is pre-drawn in this position and, by k -FAT Lemma 8.3, we get a k -FAT obstruction. Together with u and v (or possibly only one of them), we get one of the obstructions in Fig. 29. \square

Lemma 8.9. *If I_a is on the left of I_c , $P(b) \setminus P(c) \neq \emptyset$ and $P(a) \subsetneq P(c)$, then G and \mathcal{R}' contain a k -FAT, $(k, 1)$ -CE, k -FS, k -FDS, k -FNS, or k -EFS obstruction.*

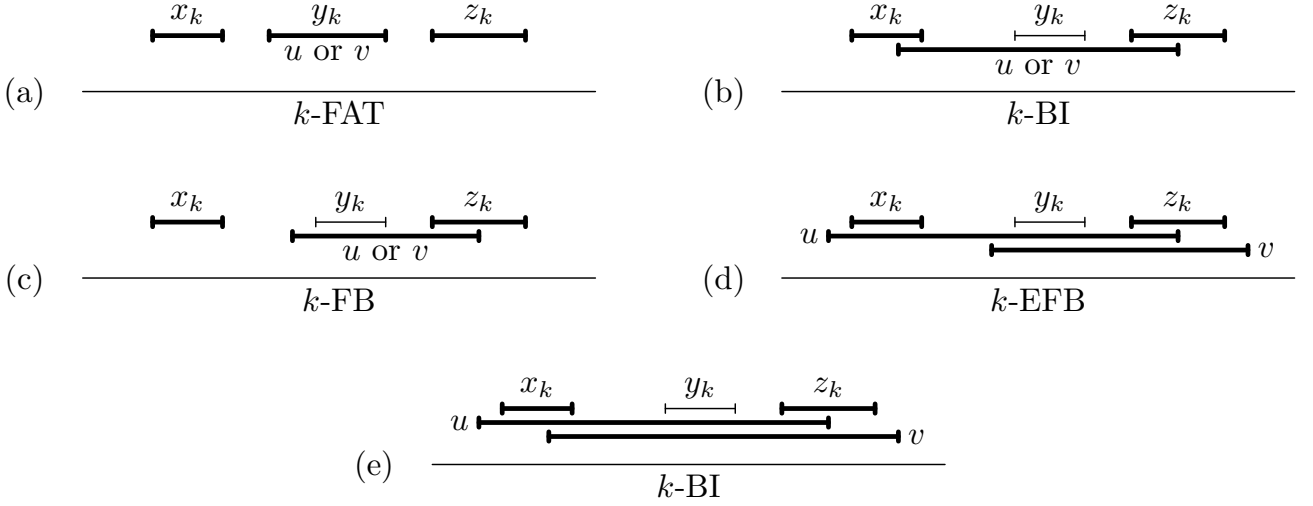


Fig. 29. The different obstructions obtained in the proof of Lemma 8.8. If $\ell(x_k) \leq \ell(u) \leq r(u) \leq r(z_k)$, we get one of the obstructions (a) to (c). Since z_k is in the Q-node between x_k and c , if u or v intersect x_k , then they also intersect z_k . In the cases (d) and (e), $\ell(u) < \ell(x_k)$ and $r(z_k) < r(v)$. Since u intersects z_k , there are only two possible obstructions.

Proof. We choose $r \in P(b) \setminus P(c)$ and $q \in P(c) \setminus P(a)$ with leftmost right endpoint. Then $\langle r \rangle'$ is on the right of I_c and $\langle q \rangle'$ is on the right of I_a . We note that q might be adjacent to r or not, and might belong to $P(b)$ or not. Since $P(a) \subsetneq P(c)$, we get from the structure of the Q-node that also $P(a) \subsetneq P(b)$. Let $u \in P^{\leftarrow}(a)$. Notice that at least one of q and u belongs to $P^{\leftarrow}(c)$.

Case 1: $u \in P^{\leftarrow}(c)$. Then $r(u) \leq r(q)$ and $P(c) \subsetneq P(b)$; the situation is depicted in Fig. 30a. We apply Sliding Lemma 4.4 to I_c , I_b , and r . We get a pre-drawn interval $z_k \notin P(c)$ covering $r(u)$, and a path P_{r,z_k} consisting of pre-drawn intervals not contained in $P(c)$. Therefore, z_k is on left of c in the Q-node. Since I_a is on the left of I_c , all vertices of P_{r,z_k} are also not contained in $P(a)$. Thus z_k is on the right of a in the Q-node.

Choose $y_k \in c$ non-adjacent to z_k . By Lemma 3.5, there exists $x_k \in a$ non-adjacent to both z_k and q . Since z_k is between a and c in the Q-node, also x_k is non-adjacent to y_k . Since $y_k q z_k$ is a path avoiding $N[x_k]$, by (k, ℓ) -CE Lemma 8.5 we obtain a $(k, 1)$ -CE obstruction.

Case 2: $q \in P^{\leftarrow}(c)$. Then $r(q) < r(u)$. First we argue that, without loss of generality, we can assume that either $\langle q \rangle'$ and $\langle r \rangle'$ are disjoint, or $\langle r \rangle'$ covers $r(q)$. Suppose that $\langle r \rangle'$ is contained in $\langle q \rangle'$. Since $q \in P^{\leftarrow}(c)$, this implies that $P(c) \subsetneq P(b)$. By applying Sliding Lemma 4.4 to I_c , I_b and r , we obtain a pre-drawn interval \tilde{r} not in $P(c)$ which covers $r(q)$. We also get a path $P_{r,\tilde{r}}$ whose vertices are pre-drawn and not contained in $P(c)$; since I_a is on the left of I_c , they are also not in $P(a)$. Therefore \tilde{r} is between a and c in the Q-node. Further, \tilde{r} belongs to some clique \tilde{b} for which $I_{\tilde{b}}$ is on the right of I_c . From now

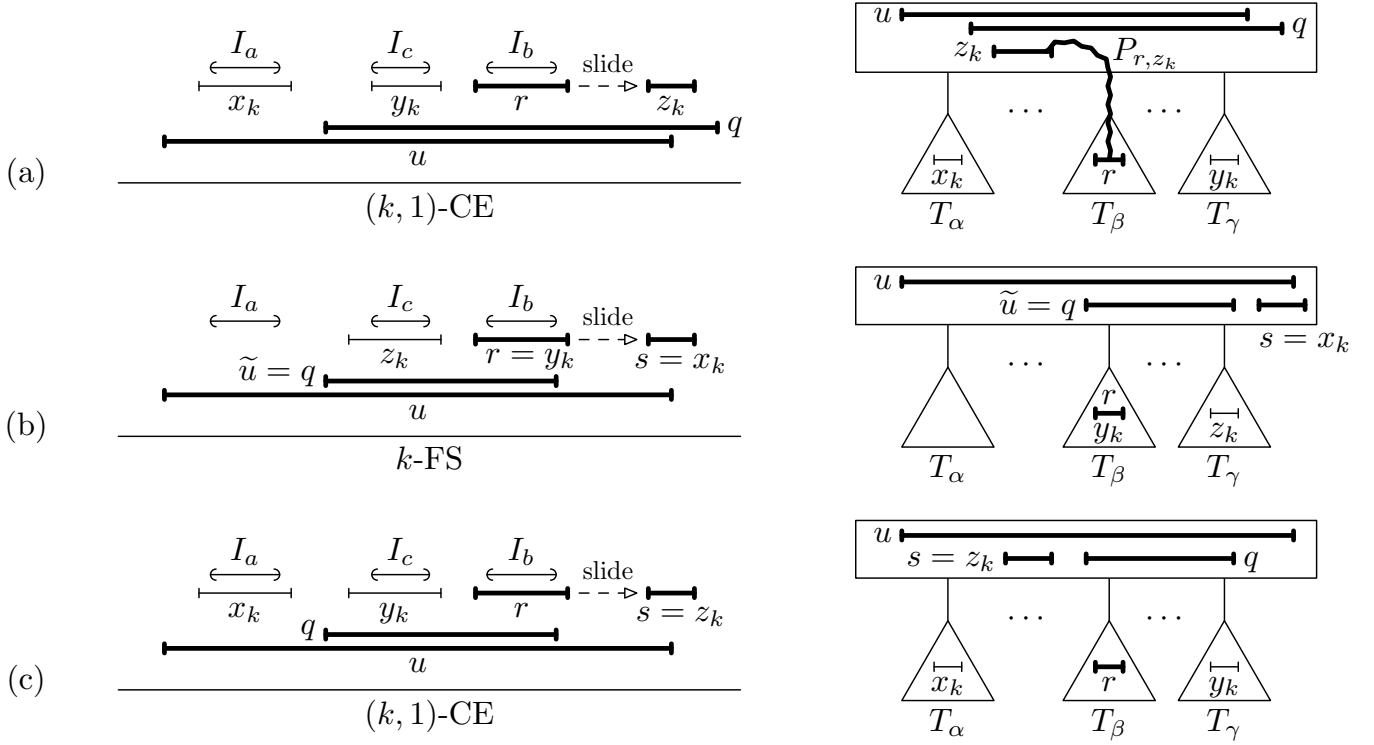


Fig. 30. Proof of Lemma 8.9. On the left, the pre-drawn intervals. On the right, their positions in the MPQ-tree. (a) Case 1. (b) Subcase 2A. (c) Subcase 2B.

on, we work with \tilde{r} as r , and with \tilde{b} as b . Hence the assumption on the relative positions of $\langle q \rangle'$ and $\langle r \rangle'$ holds.

We apply Sliding Lemma 4.4 to I_a , I_b and r , and we get a pre-drawn interval $s \notin P(a)$ covering $r(u)$. This sliding is weaker than in Case 1: we know that s is on the right of a , but we do not know its position with respect to c . We distinguish three subcases according to the relative positions of q and s in the Q-node.

Subcase 2A: s is on the right of q . The situation is depicted in Fig. 30b. Let $x_k = s$ and $y_k = r$. If $\langle q \rangle'$ is on the left of $\langle r \rangle'$, let $z_k = q$. Otherwise, let $z_k \in c$ be a vertex non-adjacent to r , but possibly adjacent to x_k . Since in every extending representation z_k is placed on the left of y_k , we can apply k -FAT Lemma 8.3 to x_k , y_k and z_k , and get a subgraph H_k . If $\langle q \rangle'$ is on the left of $\langle r \rangle'$, then H_k gives a k -FAT obstruction. If $\langle r \rangle'$ covers $r(q)$, then H_k together with $\tilde{u} = q$ gives a k -FS obstruction.

Subcase 2B: s is on the left of q . We choose $x_k \in a$ and $y_k \in c$ non-adjacent to s ; such vertices exist because s is between a and c in the Q-node. By (k, ℓ) -CE Lemma 8.5, we get a (k, ℓ) -CE obstruction for x_k , y_k , $z_k = s$ and u . Notice that we can construct a path P_{y_k, z_k} from y_k to z_k avoiding $N[x_k]$ by applying Sliding Lemma 4.4 to I_a , I_c , and q . Thus $\ell = 1$.

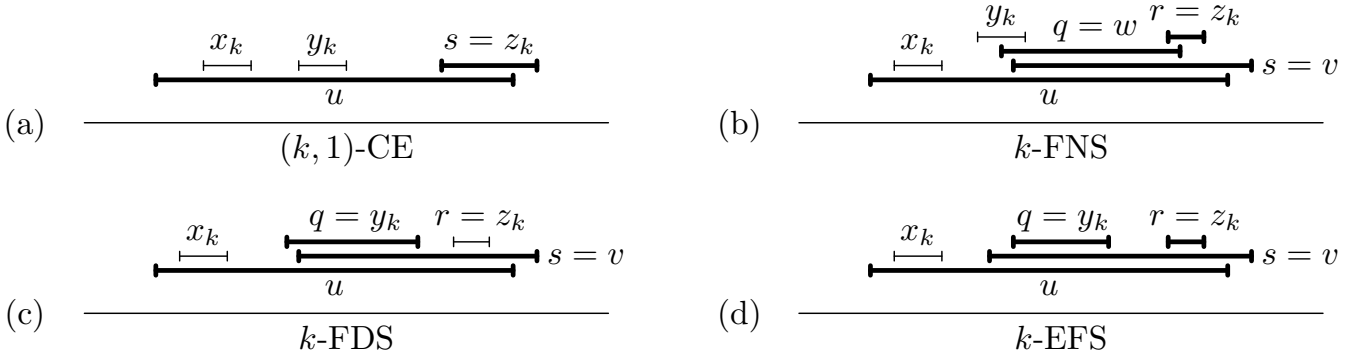


Fig. 31. Four possible obstructions obtained in Subcase 2C of the proof of Lemma 8.9. (a) If $s \notin P(c)$, we get a $(k, 1)$ -CE obstruction. (b) If $\langle q \rangle'$ intersects $\langle r \rangle'$, we get a k -FNS obstruction. Recall that the relative order of $\ell(q)$ and $\ell(s)$ does not matter. (c) If $\langle q \rangle'$ is on the left of $\langle r \rangle'$ and $\ell(q) \leq \ell(s)$, we get a k -FDS obstruction. (d) If $\langle q \rangle'$ is on the left of $\langle r \rangle'$ and $\ell(s) < \ell(q)$, we get a k -EFS obstruction.

Subcase 2C: $\langle s \rangle'$ intersects $\langle q \rangle'$. Notice that $\langle s \rangle'$ also intersects $\langle r \rangle'$. Therefore, if $s \notin P(c)$, then it appears in the Q-node between a and c . Let $z_k = s$, we get a $(k, 1)$ -CE obstruction as follows. We choose $y_k \in c$ non-adjacent to z_k . By Lemma 3.5, there exists $x_k \in a$ non-adjacent to q , y_k , and z_k . By (k, ℓ) -CE Lemma 8.5, we get a $(k, 1)$ -CE obstruction for x_k, y_k, z_k and u as illustrated in Fig. 31a; notice that the path $y_k q z_k$ avoids $N[x_k]$.

It remains to deal with the situation when $s \in P(c)$. Let $z_k = r$. If $\langle q \rangle'$ intersects $\langle r \rangle'$, let $y_k \in c$ be a vertex non-adjacent to r ; otherwise let $y_k = q$. By Lemma 3.5, there exists $x_k \in a$ non-adjacent to q , y_k , and z_k . In every extending representation, $\langle y_k \rangle$ is placed on the left of $\langle z_k \rangle'$, and $\langle x_k \rangle$ is placed on the left of $\langle y_k \rangle$. Therefore, by k -FAT Lemma 8.3, we get a subgraph H_k of a k -FAT obstruction. Together with $u, v = s, w = q$ (for $y_k \neq q$), or possibly some of them, we get a k -FDS, k -EFS, or k -FNS obstruction; see Fig. 31b, c, and d. \square

The case where $P(b) \subsetneq P(c)$ is addressed in Lemmas 8.11 and 8.12. First, we need an auxiliary result.

Lemma 8.10. *If I_a is on the left of I_c and $P(b) \subsetneq P(c)$, there exist $q \in P(c) \setminus P(b)$ and $r \in P(b) \setminus P(a)$ such that $\langle q \rangle'$ is on the right of I_a and on the left of I_b , and $\langle r \rangle'$ is on the right of I_a , containing I_c and I_b . Without loss of generality, $\langle q \rangle'$ covers $\ell(r)$.*

Proof. The proof is depicted in Fig. 32. Clearly, there exists $q \in P(c) \setminus P(b)$. Due to the structure of the Q-node, we also have that $q \notin P(a)$. Therefore, $\langle q \rangle'$ is between I_a and I_b .

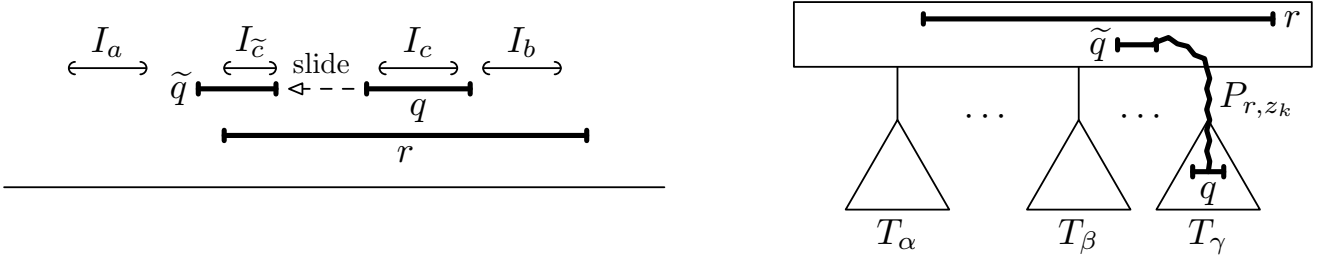


Fig. 32. Proof of Lemma 8.10. On the left, the pre-drawn intervals. On the right, their positions in the MPQ-tree.

Next, we argue that there exists $r \in P(b) \setminus P(a)$. For contradiction, assume that $P(b) \subsetneq P(a)$. Let $v \in P^{\rightarrow}(b)$; notice that v contains I_a and I_c . By the flipped version of Sliding Lemma 4.4 applied to I_c , I_b and q , there exists a path consisting of pre-drawn intervals not contained in $P(b)$ from q to z , where $\langle z \rangle'$ covers $\ell(v)$. At least one interval of this path intersects I_a , so it belongs to $P(a)$. This contradicts the fact that b is between a and c in the Q-node. Hence, there exists $r \in P(b) \setminus P(a)$.

We choose r having rightmost left endpoint. Clearly, $\langle r \rangle'$ is on the right of I_a , and contains I_b and I_c . Suppose that $\ell(r) < \ell(q)$. Since r has rightmost left endpoint among all intervals in $P(b) \setminus P(a)$, and every interval in $P(a)$ has its left endpoint more to the left, we obtain that $r \in P^{\rightarrow}(b)$. Therefore, we can apply the flipped version of Sliding Lemma 4.4 to I_c , I_b and q . We get a pre-drawn interval $\tilde{q} \notin P(b)$ covering $\ell(r)$, and a path $P_{q, \tilde{q}}$ from q to \tilde{q} whose vertices are not in b . Therefore, \tilde{q} is on the right of b in the Q-node. Let \tilde{c} be a maximal clique containing \tilde{q} . Since $I_{\tilde{c}}$ is contained in \tilde{q} , it is between I_a and I_b . Therefore, we can work with \tilde{q} and \tilde{c} instead of q and c . Thus we can assume that $\langle q \rangle'$ covers $\ell(r)$. \square

For $P(b) \subsetneq P(c)$, we distinguish two cases.

Lemma 8.11. *If I_a is on the left of I_c , $P(b) \subsetneq P(c)$, and $P(a) \setminus P(c) \neq \emptyset$, then G and \mathcal{R}' contain a k -FS obstruction.*

Proof. The proof is illustrated in Fig. 33. By Lemma 8.10, there exist $q \in P(c) \setminus P(b)$ and $r \in P(b) \setminus P(a)$ such that $\langle q \rangle'$ covers $\ell(r)$. Let $x_k \in P(a) \setminus P(c)$ and $y_k = q$. Then $\langle x_k \rangle'$ is on the left of I_c , and therefore also on the left of I_b . Thus $x_k \notin P(b)$. We infer that x_k is on the left of b in the Q-node, so it is non-adjacent to y_k . In consequence, $\langle x_k \rangle'$ is on the left of $\langle y_k \rangle'$. Let $z_k \in b$ be a vertex non-adjacent to y_k .

If z_k is adjacent to x_k , we get a 1-FS obstruction. Otherwise, in every extending representation, $\langle z_k \rangle$ is to the right of $\langle y_k \rangle'$. By k -FAT Lemma 8.3,

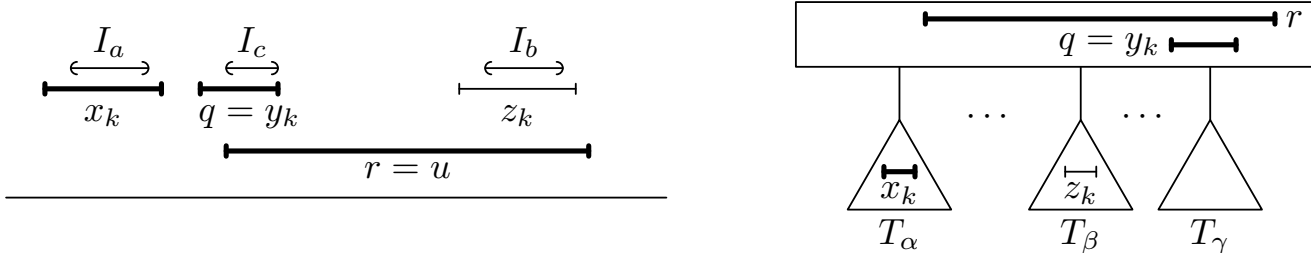


Fig. 33. Proof of Lemma 8.11. We derive that $\langle x_k \rangle'$ is on the left of $\langle q \rangle'$, which gives a k -FS obstruction based on the positions in the Q-node.

we get a subgraph H_k of a k -FAT obstruction. Together with $u = r$, this leads to a k -FS obstruction. \square

Lemma 8.12. *If I_a is on the left of I_c , $P(b) \subsetneq P(c)$ and $P(a) \subsetneq P(c)$, then G and \mathcal{R}' contain a $(k, 1)$ -CE, k -FB, k -BI, k -FDS, or k -EFDS obstruction.*

Proof. Let $p \in P^{\leftarrow}(a)$, and q be the vertex from Lemma 8.10. By applying Sliding Lemma 4.4 to I_a , I_c and q , we get a pre-drawn interval $s \notin P(a)$ covering $r(p)$, and path $P_{q,s}$ of intervals not in $P(a)$, so s appears on the right of a in the Q-node. Similarly, as in Case 2 of the proof of Lemma 8.9, we distinguish three cases according to the relative positions of s and q in the Q-node; see Fig 34.

Case 1: s is on the left of q . By Lemma 3.5, there exists $x_k \in a$ non-adjacent to all vertices of $P_{q,s}$, in particular non-adjacent to s and q . Let $y_k = q$, $z_k = s$, and $u = p$. Clearly, z_k is between x_k and y_k in the Q-node. By (k, ℓ) -CE Lemma 8.5 and the existence of P_{y_k, z_k} , we get a $(k, 1)$ -CE obstruction. Notice that $\langle y_k \rangle'$ can be made free; see Fig. 34a.

Case 2: s is on the right of q . Since q is between b and s in the Q-node, we get that $s \notin P(b)$. Let $x_k = s$, $z_k = q$, and $u = r$, where r is the vertex from Lemma 8.10. There exists $y_k \in b$ non-adjacent to z_k and, by the structure of the Q-node, also non-adjacent to x_k . Since y_k is adjacent to p and r , $\langle y_k \rangle$ is between $\langle x_k \rangle'$ and $\langle z_k \rangle'$ in every extending representation. By k -FAT Lemma 8.3, we get a subgraph H_k of a k -FAT obstruction. If $r(r) \leq r(x_k)$, together with u , we obtain a k -FB or a k -BI obstruction. If $r(r) > r(x_k)$, together with u and $v = p$, we obtain a k -BI obstruction; see Fig. 34b.

Case 3: $\langle s \rangle'$ intersects $\langle q \rangle'$. Since s contains I_b , it belongs to $P(b)$. Let $y_k = q$, $u = p$, $v = s$, and $w = r$; we note that possibly $s = r$. By Lemma 3.5, there exists $x_k \in a$ non-adjacent to y_k , v , and w . Since x_k is adjacent to u , then $\langle x_k \rangle$ is on the left of $\langle y_k \rangle'$ in every extending representation. Finally, there exists $z_k \in b$ non-adjacent to y_k . Since z_k is adjacent to u , v , and w , we have that $\langle z_k \rangle$ is on the right of $\langle y_k \rangle'$ in every extending representation.

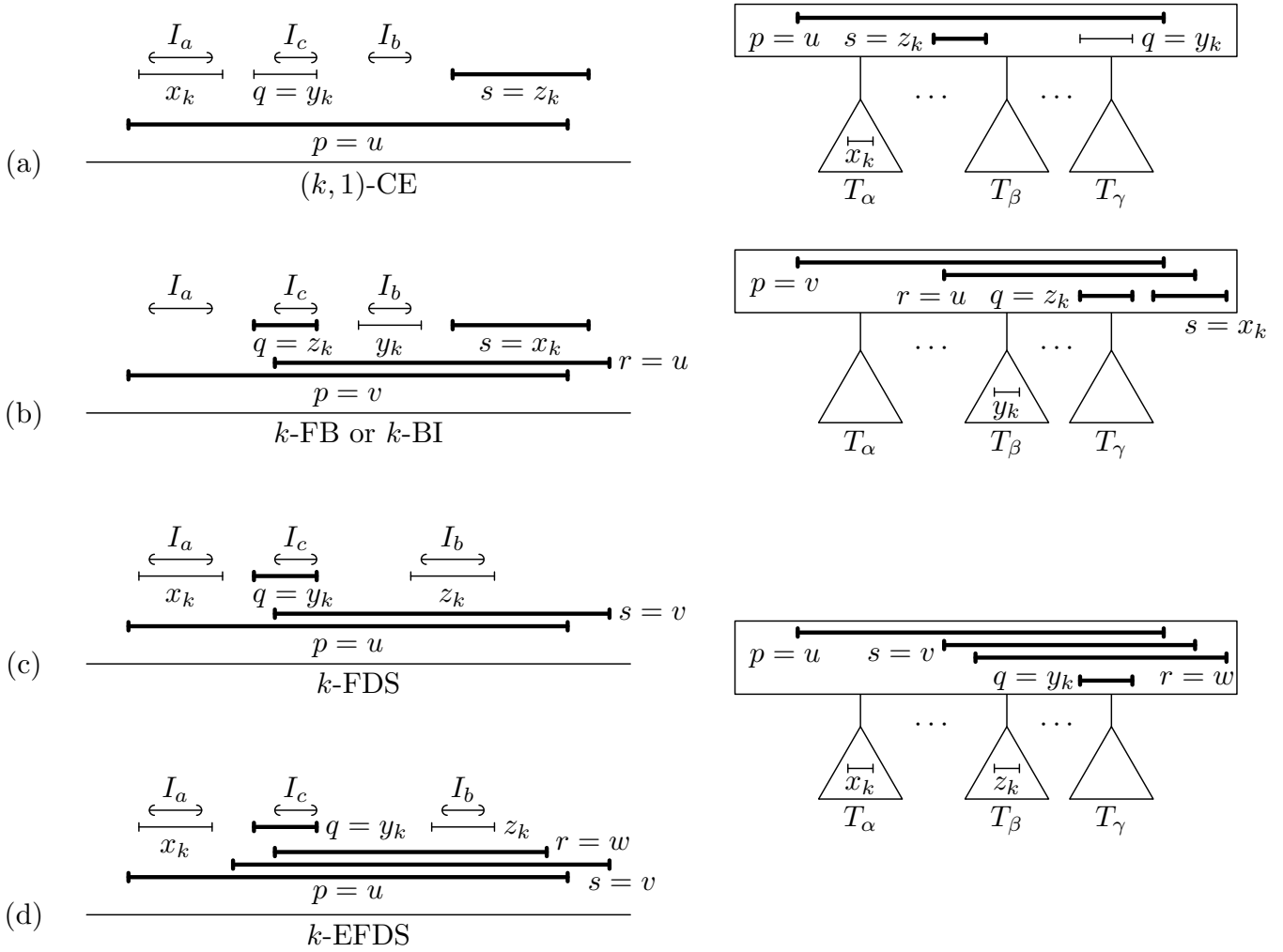


Fig. 34. Proof of Lemma 8.12. On the left, the pre-drawn intervals. On the right, their positions in the MPQ-tree. (a) Case 1. (b) Case 2. (c) Case 3, if $\ell(y_k) \leq \ell(s)$. (d) Case 3, if $\ell(y_k) > \ell(s)$.

Since z_k is between x_k and y_k in the Q-node, we can apply k -FAT Lemma 8.3, which gives a subgraph H_k of a k -FAT obstruction. If $\ell(y_k) \leq \ell(v)$, together with u and v , we obtain a k -FDS obstruction; see Fig. 34c. If $\ell(y_k) > \ell(v)$, together with u , v , and w , we get a k -EFDS obstruction; see Fig. 34d. \square

In summary, we conclude:

Lemma 8.13 (The Q-node, Three Subtrees). *If the three cliques creating the obstruction belong to three different subtrees, then G and \mathcal{R}' contain a k -FAT, k -BI ($k \leq 2$), k -FS, k -EFS, k -FB, k -EFB, k -FDS, k -EFDS, k -FNS, or (k, ℓ) -CE obstruction (either $k = \ell = 2$, or $k \geq \ell = 1$).*

Proof. For an overview, see the diagram in Fig. 26. The proof follows from Lemmas 8.6, 8.7, 8.8, 8.9, 8.10, 8.11, and 8.12. \square

9 Proofs of the Main Results

Now, we are ready to put all results together to prove the main theorem. It states that a partial representation \mathcal{R}' of G is extendible if and only if G and \mathcal{R}' contain none of the obstructions described in Section 2.

Proof (Theorem 1.1). If G and \mathcal{R}' contain one of the obstructions, they are non-extendible by Lemma 2.2. It remains to prove the converse. If G is not an interval graph, it contains an LB obstruction [26]. Otherwise, G is an interval graph and there exists an MPQ-tree T for it. By Lemma 4.1, we know that a partial representation \mathcal{R}' is extendible if and only if T can be reordered according to \triangleleft . If it cannot be reordered, then the reordering algorithm fails in some node of T . If this reordering fails in a leaf, we get a 1-BI obstruction by Lemma 6.1. If it fails in a P-node, we get an SE, 1-BI, or 1-FAT obstruction by Lemma 7.3. And if it fails in a Q-node, we get one of the obstructions of Section 2 by Lemmas 8.1, 8.2, and 8.13. \square

Next, we show that a partial representation \mathcal{R}' is extendible if and only if every quadruple of pre-drawn intervals is extendible by itself.

Proof (Corollary 1.2). The result follows from the fact that all the obstructions of Theorem 1.1 contain at most four pre-drawn intervals. \square

Concerning the certifying algorithm, we first show that k -FAT obstructions can be found in linear time:

Lemma 9.1. *Suppose that the assumptions of k -FAT Lemma 8.3 are satisfied. Then we can find a k -FAT obstruction in time $\mathcal{O}(n + m)$.*

Proof. Since the proof of k -FAT Lemma 8.3 is constructive, the algorithm follows it. Let Q be the Q-node. We search the graph $G[Q] \setminus N[y_k]$ from x_k to compute $C(x_k)$, and test whether z_k belongs to it. If it does, the algorithm stops and outputs 1-FAT. Otherwise, we compute W_k , choose t_k , and store it together with P_k . We choose x_{k-1} as in the the proof; if $s_i(Q) = s_{t_k}^{\rightarrow}(Q)$, then either $s_{x_{k-1}}^{\leftarrow}(Q) = s_{i+1}(Q)$, or x_{k-1} belongs to sections of T_{i+1} . Then we apply the rest of the algorithm recursively. It is important that then we can remove $C(x_k)$ and W_k from the graph because they are not used in the remainder of the obstruction.

Since the algorithm searches each vertex and edge of $G[Q] \setminus N[y_k]$ at most once when computing $C(x_j)$, we obtain that the algorithm runs in time $\mathcal{O}(n + m)$. \square

Similarly, a (k, ℓ) -CE obstruction can be obtained from (k, ℓ) -CE Lemma 8.5 in time $\mathcal{O}(n + m)$. Since obstructions are built constructively, we get a linear-time certifying algorithm for the partial representation extension problem:

Proof (Corollary 1.3). We can assume that G is an interval graph; otherwise we can find an LB obstruction in time $\mathcal{O}(n + m)$ using [28]. Each interval graph has $\mathcal{O}(n)$ maximal cliques of total size $\mathcal{O}(n + m)$, and that they can be found in linear time [32]. We compute the MPQ-tree T in time $\mathcal{O}(n + m)$ using [25]. Next, we use the partial representation extension algorithm of [21] in time $\mathcal{O}(n + m)$, which either finds an extending representation, or finds an obstructed node which cannot be reordered according to \triangleleft . We distinguish three cases according to the distinct types of obstructed nodes.

Case 1: A leaf cannot be reordered. We output a 1-BI obstruction in time $\mathcal{O}(n)$, by searching the partial representation.

Case 2: A P-node P cannot be reordered. From the partial representation extension algorithm, we get directly a two-cycle, ensured by Lemma 7.1, and four maximal cliques a, b, c , and d defining it. By Lemma 7.2, one of these maximal cliques can be omitted, and it can be clearly found in constant time. It remains to output an SE, 1-BI, or 1-FAT obstruction in time $\mathcal{O}(n + m)$, by following Lemma 7.3. For 1-BI and 1-FAT obstructions, we find a shortest path in $G[P] \setminus N[y_k]$ by searching the graph.

Case 3: A Q-node Q cannot be reordered. From the partial representation extension algorithm, we get four maximal cliques defining the obstruction and, by following Lemma 8.1, we can reduce it to at most three maximal cliques. An SE obstruction can be computed in time $\mathcal{O}(n + m)$. If three maximal cliques are contained in two subtrees, we follow Lemma 8.2 and output one of the obstructions in time $\mathcal{O}(n + m)$.

If three maximal cliques belong to three different subtrees, we follow the structure of the proof of Lemma 8.13. In all cases, we derive some vertices somehow placed in the Q-node and some pre-drawn intervals, which can be easily done in time $\mathcal{O}(n + m)$. Next, we either apply k -FAT Lemma, or (k, ℓ) -CE Lemma to construct the obstruction, which can be done in time $\mathcal{O}(n + m)$ by Lemma 9.1. \square

10 Conclusions

In this paper, we have described the minimal obstructions that make a partial interval representation non-extendible. There are three main points following from the proof:

1. Minimal obstructions for the partial representation extension problem are much more complicated than minimal forbidden induced subgraphs of interval graphs, characterized by Lekkerkerker and Boland [26].
2. Nevertheless, it is possible to describe these obstructions using structural results derived in [21] and in this paper. We show that almost all of these obstructions consist of three intervals x_k , y_k and z_k that are forced by the partial representation to be drawn in an incorrect left-to-right order. This incorrect placement leads to the complex zig-zag structure of a k -FAT obstruction.
3. The structure of the sections of a Q-node Q can be very intricate. Suppose that we contract in $G[Q]$ the sections of each subtree T_i into one vertex. Then we get an interval graph which has a unique interval representation up to flipping the real line. Such interval graphs have been extensively studied, see for instance [14,10,30]. Therefore, our structural results needed to find minimal obstructions may be of independent interest.

Structural Open Problems. The first open problem we propose is a characterization of minimal obstructions for other graph classes. We select those classes for which polynomial-time algorithms are known [7,18,19]. *Circle graphs* (CIRCLE) are intersection graphs of chords of a circle. *Function graphs* (FUN) are intersection graphs of continuous functions $f : [0, 1] \rightarrow \mathbb{R}$, and *permutation graphs* (PERM) are function graphs which can be represented by linear functions. *Proper interval graphs* (PROPER INT) are intersection graphs of closed intervals in which no interval is a proper subset of another interval. *Unit interval graphs* (UNIT INT) are intersection graphs of closed intervals of length one.

Problem 10.1. What are the minimal obstructions for partial representation extension of the classes CIRCLE, FUN, PERM, PROPER INT, and UNIT INT?

The second open problem involves a generalization of partial representations called *bounded representations* [2,19,33]. Suppose that a graph G is given

together with two closed intervals L_v and R_v for every vertex $v \in V(G)$. A *bounded representation* of G is a representation such that $\ell(v) \in L_v$ and $r(v) \in R_v$ for every vertex $v \in V(G)$. We call bounds *solvable* if and only if there exists a bounded representation. This generalizes partial representations: we can use singletons L_v and R_v for pre-drawn intervals and put them equal \mathbb{R} for the others.

Problem 10.2. What are minimal obstructions making bounds for interval graphs unsolvable?

Algorithmic Open Problems. We have described a linear-time certifying algorithm that can find one of the minimal obstructions in a non-extendible partial representation. There are several related computational problems, suggested by Jan Kratochvíl, for which the complexity is open:

Problem 10.3. What is the computational complexity of the problem of testing whether a given minimal obstruction is contained in G and \mathcal{R}' ?

Since a minimal obstruction contains at most four pre-drawn intervals, we can test over all subsets of at most four pre-drawn intervals whether they form an obstruction (say, by freeing the rest of them and testing whether the modified partial representation is extendible). If k is fixed, we can test whether the subgraph of a given obstruction is contained in G . Given a triple x_k, y_k and z_k forming a k -FAT obstruction, the proof of k -FAT Lemma 8.3 and the algorithm of Lemma 9.1 constructs it while minimizing k . The approach needs to be changed to check whether they also form an ℓ -FAT obstruction, for $\ell > k$.

The next problem generalizes the partial representation extension problem.

Problem 10.4. What is the computational complexity of testing whether at most ℓ pre-drawn intervals can be freed to make a partial representation extendible \mathcal{R}' ?

Similar problems are usually NP-complete. On the other hand, we propose the following reformulation which might lead to a polynomial-time algorithm. Every minimal obstruction contains at most four pre-drawn intervals. Let P be the set of pre-drawn intervals, and let \mathcal{S} consist of all subsets of P of size at most four which form an obstruction. We can clearly compute \mathcal{S} in polynomial time. Then the problem above is equivalent to finding a minimal hitting set of P and \mathcal{S} . This problem is in general NP-complete, but the extra structure given by the MPQ-tree might make it tractable.

Problem 10.5. What is the complexity of testing whether it is possible to remove at most ℓ vertices from an interval graph G to make a partial representation extendible \mathcal{R}' ?

This problem is fundamentally different from Problem 10.4, in which the partial representation \mathcal{R}' is modified. In this problem, we modify the graph G itself, changing its structure. When we remove a pre-drawn vertex, we also remove its pre-drawn interval from the partial representation. We note that the assumption that G is an interval graph is important. For general graphs G , the problem is known to be NP-complete even when $\mathcal{R}' = \emptyset$ [27].

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A Proof of Lemma 4.1

We conclude with a full proof of Lemma 4.1, reprinted from [21]. First, we prove the following simple lemma:

Lemma A.1. *Let \prec be a consecutive ordering of the maximal cliques and H be a connected induced subgraph. Then the maximal cliques containing at least one vertex of H appear consecutively in \prec .*

Proof. Consider the interval representation given by \prec with some choice of clique-points. The union U of the intervals of H is a closed intervals, so it is connected. For every clique a , its clique-point $\text{cp}(a)$ is placed on U if and only if a contains at least one vertex from H . Therefore the set of maximal cliques containing at least one vertex of H appears consecutively, with the remaining cliques on one side or the other. \square

Recall that Lemma 4.1 states that a partial representation \mathcal{R}' is extendible if and only if there exists a consecutive ordering of the maximal cliques that extends \triangleleft .

Proof (Lemma 4.1). A representation \mathcal{R} extending \mathcal{R}' gives some consecutive ordering of the maximal cliques. It is easy to observe that the constraints given by \triangleleft are necessary, so this consecutive ordering has to extend \triangleleft . It remains to show the other implication.

Suppose that we have a consecutive ordering \prec of the maximal cliques which extends \triangleleft . We construct a representation \mathcal{R} extending \mathcal{R}' as follows. We place the clique-points according to \prec from left to right, always greedily as far to the left as possible. Suppose we want to place a clique-point $\text{cp}(a)$. Let $\text{cp}(b)$ be the last placed clique-point. Consider the infimum over all the points where the clique-point $\text{cp}(a)$ can be placed and that are to the right of the clique-point $\text{cp}(b)$. If there is a single such point on the right of $\text{cp}(b)$ (equal to the infimum), we place $\text{cp}(a)$ there. Otherwise $\curvearrowright(a) < \curvearrowleft(a)$ and we place the clique-point $\text{cp}(a)$ to the right of this infimum by an appropriate epsilon, for example the distance of two closest distinct endpoints of pre-drawn intervals divided by n .

We prove by contradiction that this greedy procedure cannot fail; see Fig. 35. Let $\text{cp}(a)$ be the clique-point for which the procedure fails. Since $\text{cp}(a)$ cannot be placed, there are some clique-points placed on the right of $\curvearrowright(a)$ (or possibly on $\curvearrowleft(a)$ directly). Let $\text{cp}(b)$ be the leftmost one of them. If

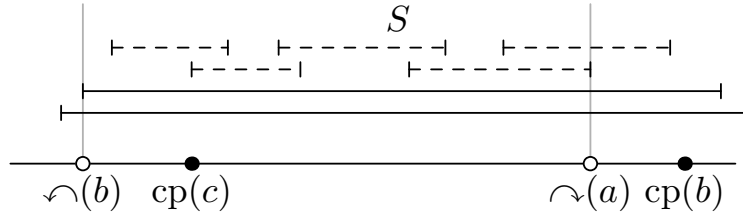


Fig. 35. An illustration of the proof: The positions of the clique-points $cp(b)$ and $cp(c)$, the intervals of S are dashed.

$\curvearrowright(b) \geq \curvearrowright(a)$, we obtain $a \triangleleft b$ which contradicts $b < a$ since $cp(b)$ was placed before $cp(a)$. So, we know that $\curvearrowright(b) < \curvearrowright(a)$. To get contradiction, we question why the clique-point $cp(b)$ was not placed on the left of $\curvearrowright(a)$.

The clique-point $cp(b)$ was not placed on the left of $\curvearrowright(a)$ because all these positions were either blocked by some other previously placed clique-points, or they are covered by some pre-drawn interval not in $P(b)$. There is at least one clique-point placed to the right of $\curvearrowright(b)$ (otherwise we could place $cp(b)$ to $\curvearrowright(b)$ or right next to it). Let $cp(c)$ be the right-most clique-point placed between $\curvearrowright(b)$ and $cp(b)$. Every point between $cp(c)$ and $\curvearrowright(a)$ has to be covered by a pre-drawn interval not in $P(b)$. Consider the set S of all the pre-drawn intervals not contained in $P(b)$ intersecting $[c, \curvearrowright(a)]$; depicted dashed in Fig. 35.

Let C be the set of all maximal cliques containing at least one vertex from S . Since S induces a connected subgraph, according to Lemma A.1 all maximal cliques of C appear consecutively in $<$. Now, a and c both belong to C , but b does not. Since $c < b$, then $a < b$ which contradicts our original assumption $b < a$. \square